

# PSS CENTRAL INSTITUTE OF VOCATIONAL EDUCATION, SHYAMLA HILLS, BHOPAL, M.P., INDIA

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PSS CENTRAL INSTITUTE OF VOCATIONAL EDUCATION, NCERT

# Preface

Vocational Education is a dynamic and evolving field, and ensuring that every student has access to quality learning materials is of paramount importance. The journey of the PSS Central Institute of Vocational Education (PSSCIVE) toward producing comprehensive and inclusive study material is rigorous and time-consuming, requiring thorough research, expert consultation, and publication by the National Council of Educational Research and Training (NCERT). However, the absence of finalized study material should not impede the educational progress of our students. In response to this necessity we present the draft study material, a provisional yet comprehensive study designed to bridge the gap between teaching and learning, until the official version of the study material is made available by the NCERT. The oraft study material provides a structured and accessible set of materials for teachers and students to utilize in the interim period. The content is aligned with the prescribed curriculum to ensure that students remain on track with their learning objectives.

The contents of the modules are curated to provide continuity in education and maintain the momentum of teaching-learning in vocational education. It encompasses essential concepts and skills afigned with the curriculum and educational standards. We extend our gratitude to the academicians, vocational educators, subject matter experts, industry experts, academic consultants, and all other people who contributed their expertise and insights to the creation of the draft study material.

Teachers are encouraged to use the draft modules of the study material as a guide and supplement their eaching with additional resources and activities that cater to their students unique learning styles and needs. Collaboration and feedback are vital cherefore, we welcome suggestions for improvement, especially by the teachers, in improving upon the content of the study material.

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Deepak Paliwal (Joint Director) PSSCIVE.

Date: 12 March 2025 Bhopal

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# **MODULE 1**

# ASSEMBLY AND DISASSEMBLY PROCESSES OF DRONE

# **Module Overview**

This module provides an in-depth understanding of the assembly and disassembly processes essential for drone technicians. It covers the step-by-step procedures involved in building custom drones, maintaining pre-built models, and troubleshooting issues efficiently.

Learners will explore component selection, she handling techniques, and post-flight maintenance to ensure optimal drone performance and longevity. By mastering these processes, technicians can enhance drone reliability, safety, and functionality in vacous applications.

# Learning Outcomes

After completing this module, you will be able to:

- Explain the process of assembling and disassembling different types of drones.
- Identify and describe key our ponents involved in drone assembly and disassembly.
- Understand the power architecture of a drone, including battery, power distribution, and energy management.
- Explain the software architecture of drones, including firmware, control algorithms, and flight controllers.
- Describe the communication module of a drone, including remote control, takenetry, and data transmission systems.
- Discuss the various methods of solar power generation, including photovoltaic.

Explore the future potential of solar energy in contributing to global energy needs and sustainability goals.

# **Module Structure**

Session 1: Describe the Assembling/disassembling different types of Drones

Session 2: Describe Power Architecture of drone

Session 3: Describe Software Architecture and Communication Module

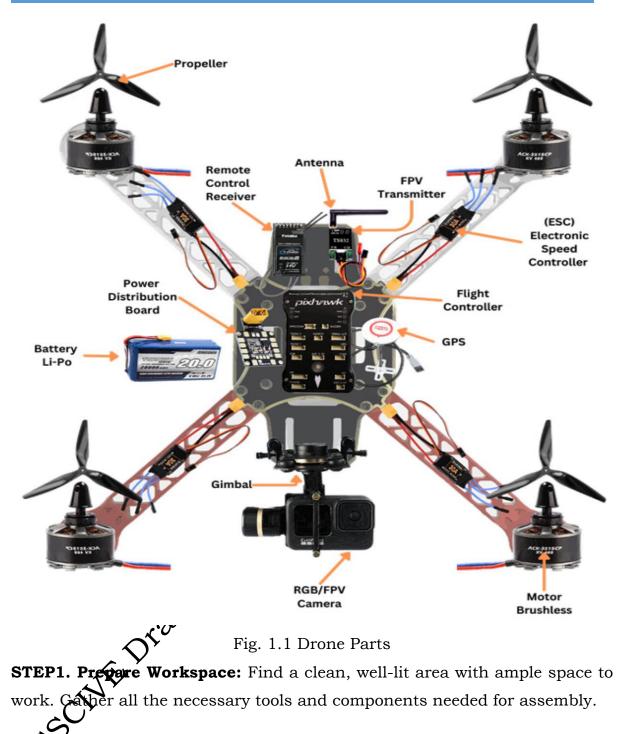
#### INTRODUCTION

Assembly and disassembly processes of drones are essential for drone technician. Whether you're building a custom drone from scratch or performing routine maintenance on a pre-built model, understanding these processes ensures safe operation, efficient troubleshooting, and optimal performance. In this chapter, we explore into the difficulties of assembling and disassembling drones, covering everything from selecting components to performing post-flight maintenance.

SESSION 1: DESCRIBE THE ASSEMBLING/DISASSEMBLING OF DRONE **ASSEMBLING OF DRONE:** Assembly means consisting of а components of drone that are fitted together. The assembly process of a drone involves carefully putting together its components to ensure proper functionality. Start by assembling the frame by securing the base and arms using screws. Next, attach the motors to the ends of the arms and fix the propellers, ensuring they are properly argined. Install the flight controller at the center of the frame and connector to the power distribution board. Then, mount the GPS module, telemetry system, and LED indicators, making sure all electronic components are securely wired. Attach the battery to its designated holder and connect it to the power module. If the drone includes a camera or gimbal carefully mount and connect it. Finally, double-check all connections, when screws, and ensure the wiring is properly managed. Before flying perform a test to verify that all components are functioning correct

 $\mathbf{x}$  The assembly process can vary based on the type of drone, whether it's a commercially available model. Here's a general overview of the steps involved in assembling a drone.

Before starting to assemble the drone, it is important to know about its main parts and following steps regarding assembly of drone.



#### DRONE SERVICE TECHNICIAN GRADE XII



Fig. 1.2 Workspace

**STEP2. Frame Assembly:** Start by laying out the drone frame components. This typically includes the main body, arms, and landing gear. Follow the manufacturer's instructions to securely assemble the frame using screws or bolts.



Fig. 1.3 Drone frame and landing gear

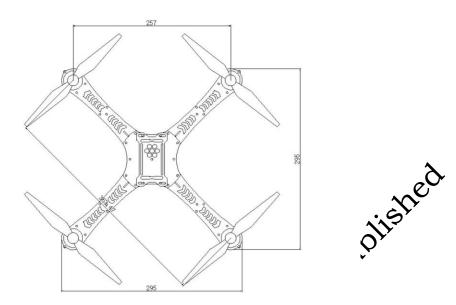


Fig. 1.4 Top view of drone **STEP3. Install Motors:** Attach the brushless motors to each arm of the frame using the provided screws. Ensure that the motor wires are facing inward towards the center of the frame for asier wiring later on.



Fig. 1.5 Brushless motors

**Mount Electronic Speed Controllers (ESCs):** Connect each motor to its corresponding ESC. Mount the ESCs onto the frame, typically below the motors, using double-sided tape or zip ties.

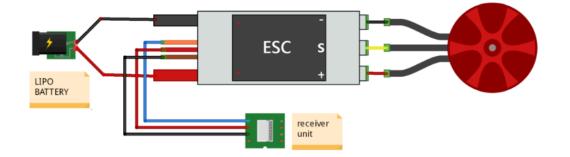
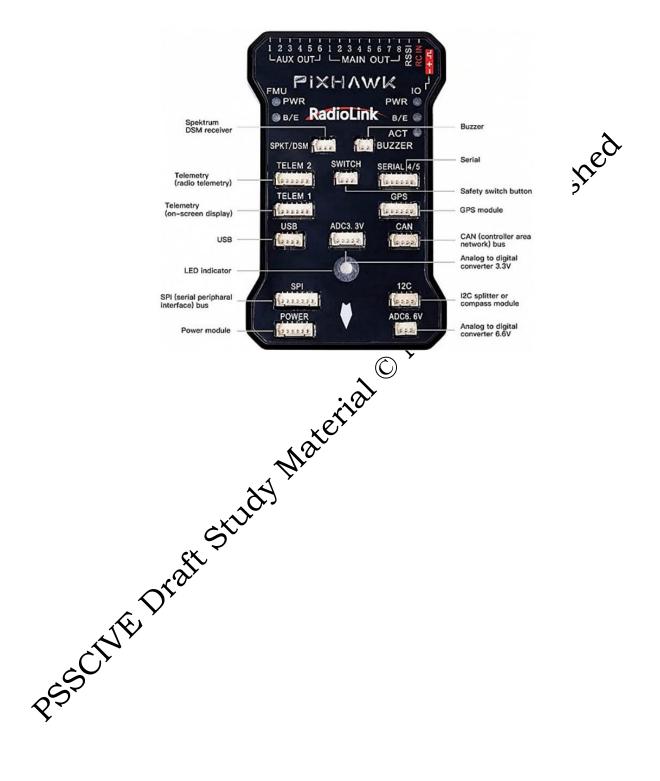


Fig. 1.6 Line diagram of Electronic Speed Controllers

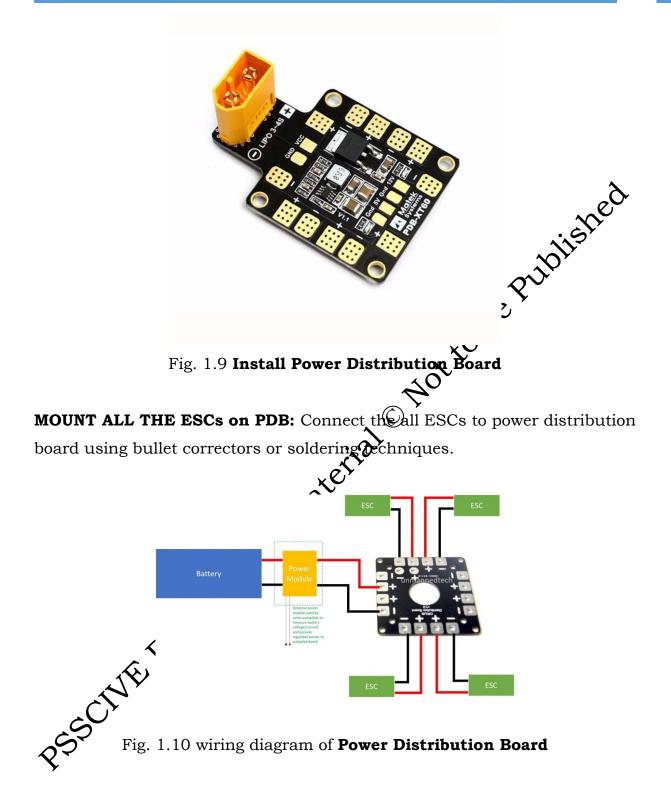


# g. 1.7 Electronic Speed Controllers

Attach Flight ontroller: Mount the flight controller onto the frame, usually at the center or top. Connect the ESCs to the flight controller according to the wiring diagram provided with the controller. The flight controller should be placed on the frame as close as possible to the centreorgravity (CoG), top-side up, and oriented so that the heading mark arrow points towards the front of the vehicle. Vibration isolation is often needed, and you should follow the manufacturer recommendations. This Pixhawk flight controller from RadioLink has optimized the PCB layout and the barometer height hold, providing more stable flight performance even at high speed. It integrated the newest 32-bit chip technology and high-end sensors, this is absolutely one of the best flight controllers for quadcopters. 6





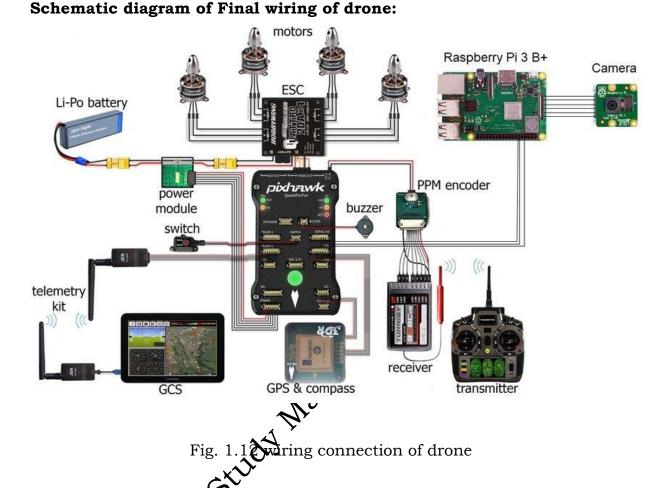


**Connect Other Components:** Install any additional components such as GPS modules, cameras, or sensors according to the manufacturer's instructions. Connect their cables to the appropriate ports on the flight

controller.



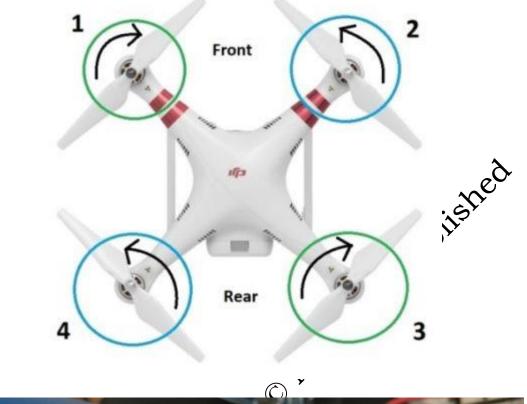
**Secure Battery:** Mount the battery onto the frame using Velcro straps or a battery tray. Ensure that it is securely fastened and balanced to maintain stability during flight.



**Check Connections and Calibration:** Double-check all connections and wiring to ensure they are secure and correctly configured. Calibrate the flight controller according to the manufacturer's instructions.

There are several drone calibration software options available depending on the type of drone and its use commercial, racing, or DIY (Do It Yang) builds.

**Attach Propellers:** Carefully attach the propellers to the motor shafts, making sure to match the direction indicated by the manufacturer (clockwise or counterclockwise). Tighten the propeller nuts securely.





## List of Useful Software for Drone Setup and Calibrations

In the below table showing the few drones Open-Source & DIY Drone Calibration Software:

#### **Open-Source & DIY Drone Calibration Software**

S.No	Software	Platform	Key Features	Best For
1.	Betaflight Configurator	Windows, macOS, Linux, Chrome	IMU calibration, motor testing, PID tuning	FPV racing drones, DIY builds
2.	Mission Planner	Windows	GPS, compass calibration, flight path planning	ArduPilot-based drones, DIY builds
3.	QGroundControl	Windows, macOS, Linux, iOS, Android	IMU, compass, GPS calibration, firmware updates	PX4 and ArduPilot drones
4.	Cleanflight Configurator	Windows, macOS, Linux, Chrome	Basic drone calibration, flight controller setup	DIY and racing drones
5.	INAV Configurator	Windows, macOS, Linux	GPS and barometer calibration, navigation tuning	Long-range and GPS-based DIY drones

Mission Planner is powerful open-source ground control software designed for drones running and ArduPilot firmware. It's mainly used for configuring, calibrating, and monitoring autonomous drones. This tool is popular among DIY builders' researchers, and professionals working with custom-built UAVs.

# Key Features of Mession Planner

- $\Rightarrow$  Calibration Tools: IMU, compass, radio, ESC, and accelerometer calibration.
- $\Rightarrow$  Configuration: Set geofences, waypoints, and RTL (Return to Launch) behavior.
  - $\Rightarrow$  Flight Planning: Create and upload autonomous missions using waypoints and commands.
  - ⇒ Live Telemetry Data: Monitor flight stats in real-time, including altitude, battery voltage, and GPS strength.
  - $\Rightarrow$  Data Logging: Review logs for post-flight analysis.
  - $\Rightarrow$  Firmware Updates: Easily install or update ArduPilot firmware.

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 $\Rightarrow$  Simulation Mode: Test missions and settings without flying a real drone.

# Minimum System Requirements for Mission Planner and other drone software:

OS: Windows (native), Linux/Mac via emulator

Processor: Intel i3 or higher

RAM: 4GB minimum

Connectivity: USB, Telemetry Radio, or Wi-Fi

# itshed CONTROLIÈER STEPS TO CONFIGURE PIXHAWK FLIGHT ve MISSION PLANNER

# STEP 01: How to Download and Install Mission Planne

- ✓ Visit the Mission Planner Download Page
- $\checkmark$  Download the latest stable version for  $\hat{W}$  ndows.

# STEP 02: Run the installer and follow the setup instructions

- ✓ Connect your drone via ₩SB or telemetry radio for initial setup.
- ✓ Basic Calibration Ster Using Mission Planner.

#### STEP 03: Connect X fur Drone

- Plug your hight controller into your PC via USB.
- 🏟 "Ćonnect" in Mission Planner.

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Fig. 1.14 Home screen of mission planter

#### **STEP 04: Firmware installation**

10<sup>× ×0</sup> ✓ Install the latest firmware based on the specification of the flight controller

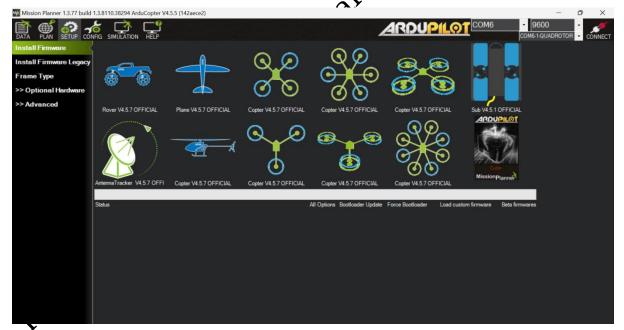
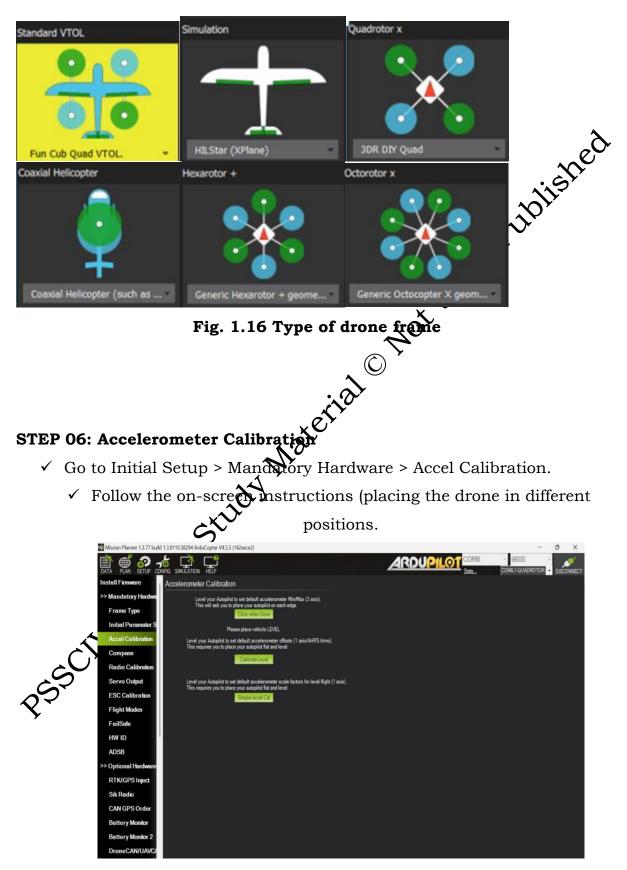


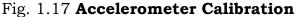
Fig. 1.15 Firmware Installation

#### STEP 05: Select the type of drone frame

 $\checkmark$  Mission planner supports all type of frames including multi-rotors, Fixed wings, VTOL (Vertical Take-off and Landing) and their combinations.

 $\checkmark$  Select frame as per as your drone.



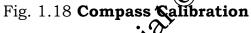


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#### **STEP 07: Compass Calibration**

- ✓ Navigate to Mandatory Hardware > Compass.
- ✓ Click "Live Calibration" and rotate the drone as directed.

Mission Planner 1.3.77 bi	ild 1.3.8110.38294 ArduCopter V4.5.5 (142aece2)	- 0 ×
DATA PLAN SETUP		COM6-1-QUADROTOR DISCONNECT
Install Firmware	Compass Priority	
>> Mandatory Hardwa	Set the Compass Priority by reordering the compasses in the table below (Highest at the top)	
Frame Type	Phonty DevID BusType Bus Address DevType Masing External Orientation Up Down 1 658953 I2C 1 14 IST8310 None V 1	
Initial Paramater S		
		<b>^</b>
Accel Calibration		
Compass		ed
Radio Calibration		
Servo Output		Í
ESC Calibration		
Flight Modes	Do you want to disable any of the first 3 compasses?	
FailSafe	A reboot is required to adjust the ordering.	
	Reboot	
HW ID	A mag calibration is required to remap the above changes. Onboard Mag Calibration	
ADSB	Start Accept Cancel	
>> Optional Hardware	Mag 1	
RTK/GPS Inject		
Sik Radio	Mag 2	
CAN GPS Order	Mag 3 Vite Stress if calibration fails	
Battery Monitor		
	Large Vehicle MagCal	
Battery Monitor 2		
DroneCAN/UAVC		
	$(\bigcirc)$	

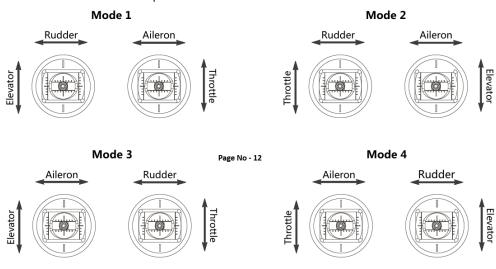


# **STEP 08: Radio Calibration**

- ze ✓ Go to Radio Calibration under Mandatory Hardware.
- $\checkmark$  Turn ON the transmitted and bind it to its receiver, select the stick
- Different mode shown in the below image ✓ Move all sticks on your transmitter to the full range and confirm

#### DRONE SERVICE TECHNICIAN GRADE XII





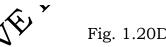


Fig. 1.20Different stick modes for flying

# STEP 9: ESC Calibration

Remove propellers for safety.

 Navigate to Initial Setup > ESC Calibration and follow the guided steps.

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Mission Planner 1.3.77 build	d 1.3.8110.38294 Ardu	duCopter V4.5.5 (1-	42aece2)							- ā	×	
		Г <mark>Р</mark> НЕСР				ARDU	PILOT s	OM6 tats	- 9600 Com6-1-QUADROT	· 'OR • D		
Install Firmware	ESC Calibrat	tion (AC3.3+)										
>> Mandatory Hardwa	Calibrate ESCs	Remove Props!										
Frame Type	Calibrate Loca	After pushing thi -Disconnect US -Plug in battery	s button: 3 and battery									
Initial Paramater S		-when LEDs flas	h, push Saftey Switch (if pre ep as they are calibrated	sent)								
Accel Calibration		- restart flight co	ntroller normally									
Compass	ESC Type:	Normal	·									
Radio Calibration	Output PWM Min	1000 🗘 Le	ave as 0 to use RX input ran	ge								
Servo Output	Output PWM Max	2000 🗘 Le	ave as 0 to use RX input ran	ge								
ESC Calibration	Spin when Armed	0.100 ≑ sp	eed when motors are armed	but throttle is at zero (idle)								
Flight Modes	Spin minimum		nimum sp <del>ee</del> d of motors while	e in flight (slightly higher t	than "Spin when Armed	ה						
FailSafe	Spin Maximum	0.950 📫 m	aximum speed of motors whil	e in flight (almost all escs	s have a deadzone at th	ne top)						N
HW ID												٣
ADSB												
>> Optional Hardware												
RTK/GPS Inject												
Sik Radio												
CAN GPS Order												
Battery Monitor												
Battery Monitor 2												
DroneCAN/UAVC/												
								٣				1

Fig. 1.21**ESC Calibration** 

## STEP 10: Flight Mode Setup

#### **Common Flight Modes in Drones:**

**Stabilized Mode (Self-Leveling Mode):** This is the most common and beginner-friendly flight mode. The drone automatically corrects itself to maintain level flight when you release the controls. It's great for beginners, as it helps keep the drone stable and easier to fly.

Altitude Hold Mode: In this mode, the drone maintains a fixed altitude, so you don't need to constantly adjust the throttle to stay at the same height. It's often used when the pilot wants to focus on horizontal movement and camera control without worrying about maintaining altitude.

**GPS Mode (Position Hold):** This mode uses GPS signals to hold the drone's position in the air. The drone will automatically stay in place (hover) even if you stop controlling it. It's useful for outdoor flights where GPS is available, providing more stable and controlled flight.

**Sport/Manual Mode:** This mode provides maximum control and responsiveness, allowing the drone to perform more aggressive maneuvers. It's typically used by experienced pilots since the drone will not automatically correct itself, and the pilot must maintain full control.

It allows for fast flying and aerial acrobatics.

Return to Home (RTH): Not strictly a "flight mode" in terms of control, but this function triggers the drone to automatically fly back to its takeoff point, typically using GPS signals. It's often used when the drone loses signal or when the battery is low.

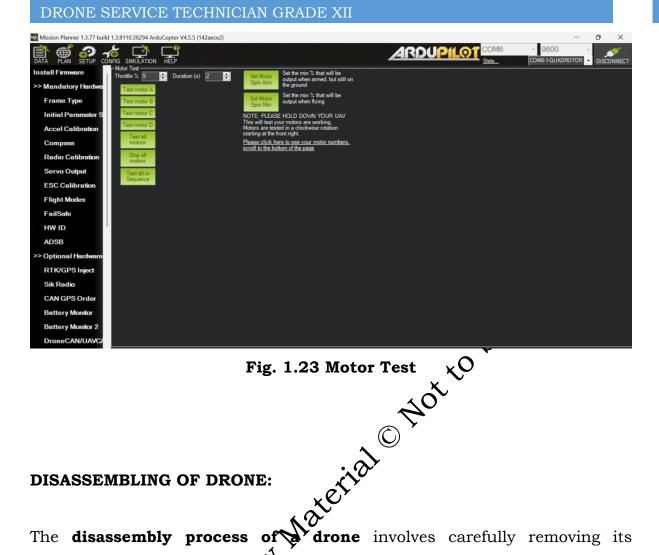
Mission Planner 1.3.77 build	d 1.3.8110.38294 Ard	uCopter V4.5.5 (142ae	ece2)				-	ð X
						OT COM6 Stats	- 9600 COM6-1-QUADROTOR	DISCONNECT
Install Firmware	c	Current Mode: AltHold						
>> Mandatory Hardwa	10	Current PWM: 5: 1500	Simple Mode	Super Simple Mode	PWM 0 - 1230			
Frame Type	Flight Mode 1	ONDOWING	Simple Mode	Super Simple Mode	PWM 1231 - 1360			
Initial Paramater S	Flight Mode 2 Flight Mode 3	Stabilize •	Simple Mode	Super Simple Mode	PWM 1361 - 1490			
Accel Calibration	Flight Mode 3	AttHold -	Simple Mode	Super Simple Mode	PWM 1491 - 1620			
	Flight Mode 5		Simple Mode	Super Simple Mode	PWM 1621 - 1749			
Compass	Flight Mode 5	PosHold •	Simple Mode	Super Simple Mode	PWM 1750 +			
Radio Calibration	r light mode o	Foshold		Simple and Super Simple				
Servo Output		Save Modes		description				
ESC Calibration								
Flight Modes								
FailSafe								
HW ID								
ADSB								
>> Optional Hardware								
RTK/GPS Inject								
Sik Radio								
CAN GPS Order								
Battery Monitor								
Battery Monitor 2								
DroneCAN/UAVC/								
					$\cdot \alpha$			

# Fig. 1.22 Flight Node Setup

Set flight modes under Intel Setup > Flight Modes (e.g., POSITION, HOLD, ALTITUDE)

# STEP 11: Test Flight

arone is functioning properly and stable. Ma adjustments to the flight controller settings if needed.  $\checkmark$  Before flying, perform a test hover in a safe, open area to ensure that the drone is functioning properly and stable. Make any necessary



## **DISASSEMBLING OF DRONE:**

The disassembly process of drone involves carefully removing its components step by step to avoid damage. First, ensure safety by turning off the drone and disconnecting the battery. Begin by removing the propellers by unscrewing them gently, followed by detaching the battery from its connector and hower. If the drone has a camera or gimbal, carefully unscrew and disconnect it. Next, unplug electronic modules such as the GPS, telemetry, LED indicators, power module, and flight controller, ensuring that all wiring connections are handled with care. Then, proceed to report the arms and motors by unscrewing their mounts, especially if the drone has foldable arms. Lastly, disassemble the drone frame by separating its plates and securing all screws and small parts in labeled containers for future use. Properly storing all components in a safe and dry place ensures they remain in good condition for reassembly or maintenance.

Disassembling a drone involves carefully removing its components in a stepby-step manner to avoid damage. We have following steps for disassembly process of a drone-

#### 1. Safety First

- Turn off the drone and disconnect the battery.
- Work on a clean surface with proper lighting.
- uplished Use the right tools like screwdrivers, pliers, and tweezers. •

#### 2. Remove the Propellers

- Hold the motor firmly and unscrew propellers (usually the ٠ counterclockwise).
- Keep them in a safe place to avoid bending or breaking. •



Fig. 1.24 Remove the Propellers

- 3. Disconnect the Battery
  - Unplug the battery connector from the mainboard.
  - any straps, clips, or holders securing the battery.



Fig. 1.25 Unplug the battery

# 4. Detach the Camera and Gimbal (if present)

- Unscrew and remove the camera mount or simbal assembly.
- Carefully disconnect camera cables without pulling too hard.



# Fig. 1.26 Detach the Camera and Gimbal

# 5. Unplug the Electronic Modules

- connect the GPS module, telemetry module, and LED indicators.
- Remove the power module and flight controller by unplugging their connectors.
  - Carefully detach the wiring harness from the board.

#### 6. Remove the Arms and Motors

- Unscrew the motor mounts and detach them from the frame.
- If the arms are foldable, carefully disassemble the hinges.

# 7. Disassemble the Frame

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- Unscrew the frame plates and separate them.
- Keep all screws, nuts, and small parts in labeled containers.

#### 8. Store the Components Properly

- Keep delicate parts in anti-static bags.
- Store everything in a dry, safe place to avoid dust and damage.

#### Check your progress:

# SESSION 1: DESCRIBE THE ASSEMBLING/DISASSEMBLING OF DIFFERENT TYPES OF DRONES

#### A. Fill in the blanks

- 1. .....the drone before disassembling any part (Always turn off)
- 2.....means a unit consisting of components of drone that are fitted together. (Assembly)
- 3. The..... manages the movement and stability of a drone. ( flight controller)
- 5. The \_\_\_\_\_\_ Speed Controllers (ESCs) regulate the power supply to the motors. (Electronic)

# B. Multiple Choice Questions

L. What is the first step in assembling a drone?

a) Attaching the propellers

b) Installing the flight controller

#### c) Assembling the frame

- d) Connecting the battery
- 2. Where the flight controller is usually mounted on a drone?
  - a) On the propellers
  - b) At the center of the frame

- c) Under the battery
- d) Near the motors
- 3. Why is it important to secure the screws properly while assembling a drone?
  - a) To make it look good

## b) To prevent vibrations and instability

- 4. What is the purpose of the power distribution board in a droit.
  a) To control the propellers
  b) To distant b) To distribute power from the battery to different components
  - c) To store flight data
  - d) To increase flight time
- 5. What should be done before flying the draw after assembly?
  - a) Directly start flying
  - b) Check all connections and test each component
  - c) Remove the propellers
  - d) Shake the drone to test stability
- 6. What is the first step in disassembling a drone?
  - a) Removing the bat
  - b) Taking off the Gome
  - c) Disconnective the GPS
  - d) Removing the motors
- sould the propellers be removed first during disassembly? 7. Why

# prevent injury or damage

- To reduce weight
- c) To increase speed
  - d) To make the drone more compact
- 8. Why is it important to store drone components properly after disassembly?

# a) To avoid losing parts and protect them from damage

b) To make the drone heavier

#### DRONE SERVICE TECHNICIAN GRADE XII

- c) To increase power consumption
- d) To improve flight performance
- 9. What step should be done before flight to ensure proper functionality?
  - a) Painting the frame
  - b) Tightening all screws
  - c) Performing a test

- Smort Answer Questions 1. What is the first step before disassembling a drone? E public 2. Why should propellers be removed first during disaster 3. Why is it important to label wires with 4. What component of the first of
- 4. What component controls the movement stability of a drone? er to the her to the waterial
  - 5. Which component provides power to the drone?

#### **SESSION 2: DESCRIBE POWER ARCHITECTURE OF DRONE**

A drone's power architecture is the intricate system that provides and manages the electrical energy required for flight and operation. It's a critical aspect of drone design, as it directly influences flight time, payload capacity, and overall performance. lished

#### **Key Components:**

#### 1. Battery:

- The primary energy source, typically a lithium ymer (LiPo) battery.
- Provides high energy density and power
- Capacity and voltage determine time and payload capacity.

# 2. Electronic Speed Controllers (ES)

- Control the speed and prection of the drone's motors.
- s DC power into AC power for the motors. Convert the battery
- Essential for pr se motor control and stability.
- 3. Motors:
  - electrical energy into mechanical energy, propelling the drone.
    - Brushless DC motors are commonly used for their efficiency and power.
  - The number and size of motors depend on the drone's size and intended use.

## 4. Propellers:

- Convert the motor's rotational energy into thrust.
- Their size, pitch, and number influence flight characteristics.

#### 5. Power Distribution Board (PDB):

- Distributes power from the battery to the ESCs, motors, and other components.
- May include fuses, switches, and current sensors for safety and monitoring.

#### **Power Flow:**

- 1. Battery: Stores electrical energy.
- 2. **PDB:** Distributes power to the ESCs.
- 3. **ESCs:** It controls the speed of motors and determined the rotation of motors by taking inputs from the flight controller or receiver. (it Converts DC power to AC power).
- 4. **Motors:** Rotate propellers, generating thrust

#### **Power Management Considerations:**

• Efficiency: Minimizing power losses in the system is crucial for maximizing flight time.

 $( \mathbb{C} )$ 

- **Thermal Management:** Anaging heat generated by the battery, ESCs, and motors is expential to prevent damage.
- **Safety:** Incorporating safety features like overcurrent protection and low-voltage alarme.
- **Reliability:** Desuring the power system is robust and can withstand the rigor of flight.

# Advanced Power Architectures:

- **Hybrid Systems:** Combining multiple power sources, such as batteries and fuel cells, for extended flight times.
  - **Solar Power:** Utilizing solar panels to recharge batteries or provide supplemental power.
  - **Energy Recovery Systems:** Capturing and reusing energy from braking or other maneuvers.

#### **Power Estimation of drone:**

Accurately estimating the power requirements of a drone is crucial for optimal design, battery selection, and performance prediction. Here's a breakdown of the key factors and methods involved:

#### **Factors Influencing Power Consumption**

- 1. **Weight:** 
  - Drone Weight: A heavier drone requires more prover to lift off and maintain flight.
  - **Payload Weight:** The weight of any attached equipment (cameras, sensors, etc.) directly impacts power consumption.

#### 2. Flight Conditions:

- Altitude: Higher altitudes mean lower air density, requiring more power to generate lift.
- Wind Speed and Direction: Wind can increase drag and energy expenditure, especially in headwinds.
  Temperature: Extreme temperatures can affect battery
- **Temperature:** Extrem temperatures can affect battery performance and more efficiency.

#### 3. Flight Mode:

- Hovering: Equires continuous power to counteract gravity.
- Forward Flight: Power consumption increases with airspeed due to increased drag.
- Maneuvers: Aggressive maneuvers like rapid turns or ascents demand higher power.

Component Efficiency:

- **Motors:** Brushless motors are generally more efficient than brushed motors.
- **Propellers:** Propeller design significantly influences thrust and power consumption.
- **Electronic Speed Controllers (ESCs):** Efficient ESCs minimize power losses during motor control.
- **Battery:** Battery chemistry and quality affect energy density and discharge rate.

#### **Power Estimation Methods**

- 1. Theoretical Calculations:
  - Thrust and Power Relationship:
    - Power = Thrust \* Velocity / Efficiency
      - Thrust can be estimated based on weight and flight conditions.
      - Velocity and efficiency depend on the specific drane design and flight mode.

The thrust to weight ratio can be calculated using this formula =  $\frac{\text{Total Thrust}}{\text{Weight of the Drone}}$ 

Where

Total Thrust is the combined thrust produced by all the motors (measured in kilograms or grams).

Weight of the Drone is the mass of the dependence, typically measured in kilograms or grams.

Best thrust to weight ratio for Drones: A thrust to weight ratio of 2:1 or higher is common, with some high-end models going up to 2.5:1 or even higher.

- Energy Consumption:
  - Energy = Power \* Time

given flight duration.

2. Experimental Testing:



- **Flight Tests:** Measuring actual power consumption during flight provides real-world data for validation and refinement of theoretical models.
- **Bench Tests:** Testing individual components (motors, ESCs) under controlled conditions can help isolate and quantify power losses.

#### **Example: Power Estimation for a Quadcopter**

1. Determine Weight:

- Drone weight (empty): 500g •
- Payload weight: 200g
- Total weight: 700g

# 2. Estimate Thrust Requirement:

For hovering, thrust must equal weight:  $700g * 9.81 \text{ m/s}^2 =$ ot to be Published 6.867 N

## 3. Assume Efficiency:

- Motor efficiency: 80%
- Propeller efficiency: 70%
- Overall efficiency: 0.8 \* 0.7 = 0.56•

# 4. Calculate Power (Hovering):

• Power = Thrust / Efficiency = 6.860.56 = 12.26 W

## 5. Estimate Flight Time:

We have using below formula for hight time calculation

Flight Time = Battery capacity h)× discharge percentage of battery / Number motors Amp drawn by single motors AAD

- Battery pacity: 2200 mAh (milliamp-hours)
- Voltage 14.8 V
- gy: 2200 mAh \* 14.8 V = 32.56 Wh (watt-hours)
- Might time: 32.56 Wh / 12.26 W = 2.65 hours (assuming constant power consumption)

**Note:** This is a simplified example. Actual power requirements can vary

Significantly depending on the specific drone design, flight conditions, and mission profile.

By carefully considering these factors and employing appropriate estimation techniques, drone designers can optimize power systems for maximum efficiency and flight endurance.

**Battery selection and sizing-** When choosing a drone battery, you can consider factors like the battery's capacity, weight, and discharge rate. You can also think about the battery's safety features, compatibility, and warranty.

Capacity: The capacity of a battery is measured in milliamp-hours (m(b))

Higher capacity batteries can provide longer flight times, but they can also be heavier. The capacity of a battery depends on the drone's size and intended use.

**Discharge rate:** The discharge rate, also known as the c rating, measures how quickly the battery can discharge. A higher C rating battery can provide more power and responsiveness, but it can also be heavier and more expensive.

**Safety:** Choose batteries with protective circuits and rigorous testing. Consider the battery's cycle life, which is the number of charge-discharge cycles it can endure.

**Compatibility:** Make sure the **battery** is compatible with your drone's requirements. Check that the battery's connector matches your drone's connector.

Warranty: Consider the warranty terms offered by the manufacturer.

# SESSION 20 DESCRIBE THE POWER ARCHITECTURE OF DRONE

# **CHECK YOUR PROGRESS**

# QA. Fill in the blanks

1. The main power source of most drones is a ......battery.

# (Lithium Polymer)

The ...... is responsible for battery power to supply the flight controller and other electronic components. (Power Distribution Board)

3. The power from the battery is distributed to the motors through

# . (Electronic Speed Controllers)

4. A drone's power architecture typically consists of a battery, PDB, ESCs, motors, and a \_\_\_\_\_. (Flight Controller)

# **1. Multiple Choice Questions**

- 1. Which type of battery is commonly used in drones?
  - a) Nickel-Cadmium (NiCd)
  - b) Lithium-Ion (Li-Ion)
  - c) Lithium Polymer (LiPo)
  - d) Lead-Acid

Published 2. What is the function of an Electronic Speed Controller

- a) Converts AC power to DC power
- b) Distributes power evenly among compa

# c) Controls the speed and direction of brushless motors

- d) Stores backup power
- 3. Why are LiPo batteries preferred ver traditional batteries in drones?

a) They are cheaper

# b) They have a higher energy density and lightweight design

- c) They can be charged faster
- d) They do not denade over time
- 4. What is the main purpose of a Power Distribution Board (PDB)?
  - a) To charge the battery

# b) To distribute power from the battery to different components

- control motor speed
- To stabilize the drone in flight

Which of the following factors determines the flight time of a drone?

# a) Battery capacity and motor efficiency

- b) Number of propellers only
- c) Type of remote control used
- d) Number of LEDs on the drone

#### SESSION 3: DESCRIBE SOFTWARE ARCHITECTURE AND **COMMUNICATION MODULE**

Drone's software architecture is the framework that governs how its various software components interact to achieve flight and perform tasks. It's a crucial aspect of drone development, as it determines the system's stability, Published reliability, and overall performance.

# **Common Architectural Patterns**

- 1. Layered Architecture:
  - Sensor Layer: Collects data from sensor Olike GPS (Global (Inertial X Measurement Positioning System), IMU Unit). barometer, and obstacle avoidance sensors.
  - Control Layer: Processes sensor data, calculates flight control signals for motors and parameters, and generates actuators.
  - Planning Layer: Plan Night paths, waypoints, and missions based on user input or autonomous algorithms (Exampleplanning a flight ssion in mission planner software).
  - Communication Layer: Handles communication with ground station x other drones, and external systems. (via telemetry or Receiver and Transmitter)

pplication Layer: Executes specific tasks like object detection, happing, or delivery, surveillance.

# 2. Real-Time Operating System (RTOS) Based Architecture:

- Utilizes an RTOS to manage tasks and resources efficiently.
- Ensures timely execution of critical flight control algorithms.
- Provides deterministic behavior and predictable response times.

#### **Key Components of Drone Software**

# 1. Flight Control System:

- Core component responsible for stabilizing the drone, controlling its attitude and position, and executing flight maneuvers.
- Employs algorithms like PID control, Kalman filtering, and sole estimation.
   vigation System:

# 2. Navigation System:

- Enables the drone to navigate to specific locations, follow хO waypoints, and avoid obstacles.
- Utilizes GPS, compass, and other sensors for localization.

# 3. Payload Control System:

onboard payloads like cameras, Manages the operation  $\sigma$ sensors, and robotic (

 $\bigcirc$ 

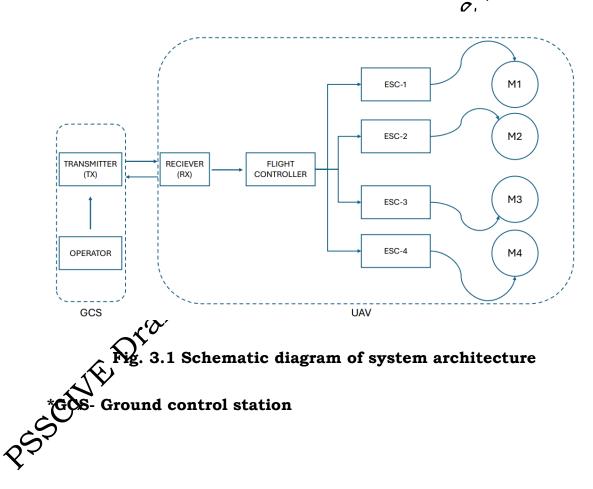
- May include image processing, data acquisition, and payload deployment mechanisms.
- 4. Communication Module:
  - Facilitates communication between the drone and ground Introl station, other drones, and external systems.

Employs various communication protocols like Wi-Fi, Bluetooth, cellular, and radio frequencies.

## **Communication Module in Drone Systems**

The communication module is a critical component of a drone's software architecture. It enables:

- **Remote Control:** Ground operators can send commands to the drone to control its flight and payload operations.
- **Telemetry Transmission:** Real-time flight data, sensor readings, and video feeds are transmitted to the ground station for monitoring and analysis.
- Data Transfer: Large amounts of data collected by the drone can be transferred to ground stations or cloud servers for storage and processing.
- Drone-to-Drone Communication: Enables communication and coordination between multiple drones for collaborative tasks.



## **Common Communication Protocols**

- **Wi-Fi:** Widely used for short-range communication, offering high bandwidth and relatively low latency.
- **Bluetooth:** Suitable for low-power, short-range communication, often used for connecting peripherals.

- **Cellular Networks:** Provide long-range connectivity, enabling communication over greater distances.
- Radio: Offers reliable long-range communication, commonly used for professional drone operations.

# **Challenges and Considerations**

- Latency: Minimizing communication latency is crucial for rea control and safe operation.
- Reliability: Ensuring reliable communication links is prevent loss of control or data.
- Security: Protecting communication channels from unauthorized хO access and interference.
- Interference: Mitigating interference from other wireless devices and environmental factors.

#### SESSION 3: DESCRIBE ARCHITECTURE AND Mate **COMMUNICATION MODULE**

# A. Fill in the Blanks

- collects data from sensors like GPS, IMU, 1. The camera. (Sensor) barometer, and
- Layer processes sensor data, calculates flight 2. The and generates control signals for motors and actuators.

\_\_\_\_ Layer plans flight paths, waypoints, and missions based on user input or autonomous algorithms. (Planning)

- 4. The Layer handles communication with ground stations, other drones, and external systems. (Communication)
  - 5. The Layer executes specific tasks like object detection, mapping, or delivery. (Application)

- 6. The core component responsible for stabilizing the drone and controlling its attitude and position is called the \_\_\_\_\_. (Flight **Control System**)
- 7. The \_\_\_\_\_\_ system enables the drone to navigate to specific locations, follow waypoints, and avoid obstacles. (Navigation)
- 8. The \_\_\_\_\_\_ Module facilitates communication between the drone

# **B.** Multiple Choice Questions

- a) Control Layer
  b) Sensor Layer
  c) Planning Layer
  d) Application Layer
  a) Navigation System
  b) Communication Market

  - laterial

    - c) Flight Control System
    - d) Payload Control System
  - 3. Which architectural partern breaks the software into small, independent serv
    - a) Layered Architecture
    - b) RTOS Arciffecture
    - c) Micro services Architecture
    - d) Mociular Architecture

at communication protocol is commonly used for short-range, high-bandwidth communication?

- a) Bluetooth
- b) Cellular Networks
- c) Wi-Fi
- d) Radio
- 5. Which system manages the operation of onboard payloads like cameras and sensors?

- a) Navigation System
- b) Payload Control System
- c) Communication Module
- d) Flight Control System
- 6. Which layer is responsible for handling communication with ground stations?
  - a) Application Layer
- 7. Which component enables the drone to navigate specific laborations and avoid obstacles?
  a) Navigation System
  b) Payload Control System
  c) Communication Module
  d) Flight Control System
  3. Which communication protocol in 1

- Material
  - a) Wi-Fi
  - b) Bluetooth
  - c) Cellular Networks
  - d) Zigbee
- 9. Which of the following rithms is commonly used in flight control systems?
  - a) PID Control
  - b) Dijkstra's Agorithm
  - c) Binary Scarch
  - d) Huffman Coding

blich factor is crucial to minimize for ensuring real-time control and afe operation?

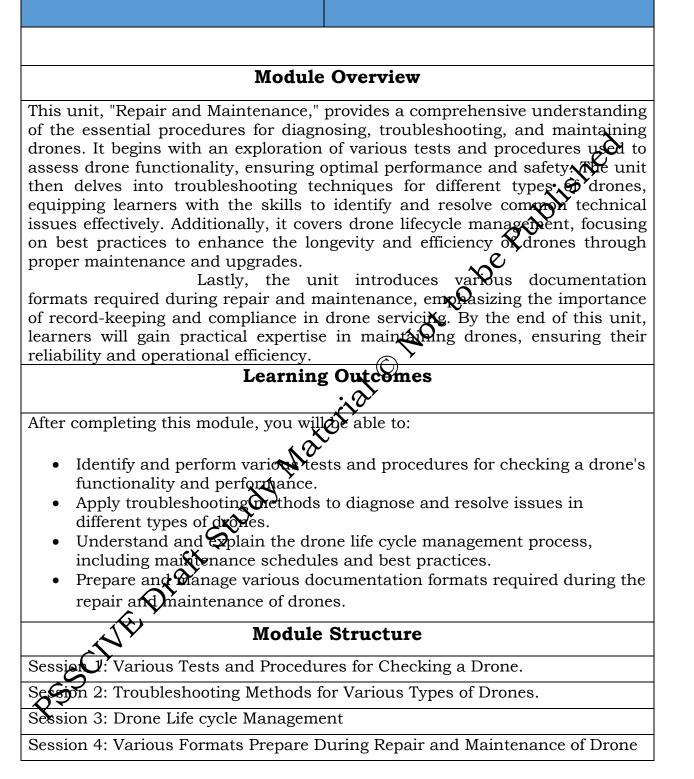
- a) Bandwidth
- b) Latency
- c) Range
- d) Frequency

# **C. Short Answer Questions**

- 1. What is the primary function of the Sensor Layer in a drone's architecture?
- 2. How does the Control Layer contribute to the drone's stability?
- 3. What are the key benefits of using a microservices Architecture for drone software?
- 4. Describe the core functions of the Flight Control System.
- 5. What are the main components used in the Navigation System and drone?
- 6. How does the Payload Control System support drone operations
- 7. What communication protocols are commonly used in the systems for long-range communication?
- 8. Why is minimizing latency important in drone communication systems?
- 9. What are some challenges faced by the tommunication Module in drone systems?

# **MODULE 2**

### **REPAIR AND MAINTENANCE**



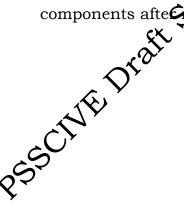
Drones have become essential tools in various industries, including aerial photography, surveying, agriculture, and defence. To ensure their reliable performance and longevity, regular maintenance and timely repairs are crucial. Proper care prevents unexpected failures, enhances flight safety, and extends the lifespan of drone components.

# **Importance of Drone Maintenance**

- Ensures Safe Operation: Reduces the risk of crashes due to mechanical or electronic failures.
- Improves Performance: Keeps motors, propellers, and batteries in optimal condition.
- Extends Lifespan: Prevents excessive wear and tear components.
- Reduces Repair Costs: Early detection of issues minimized replacements.
   pes of Drone Maintenance es expensive

## **Types of Drone Maintenance**

- 1. Routine Maintenance: Regular inspections and cleaning various components to prevent damage.  $\cdot, \circ$
- 2. Preventive Maintenance: Generally it is systematic inspection, detection and prevention failure potential Checking firmware updates, battery health, and calibration to avoid failures.
- 3. Corrective Maintenance: Repairing or replacing damaged components afte alfunctions



# SESSION 1: VARIOUS TESTS AND PROCEDURES FOR CHECKING A DRONE

The Checking a drone involves multiple tests and procedures to ensure it operates safely, efficiently, and within regulations. These tests can be categorized into pre-flight checks, functional tests, performance tests, and post-flight checks. Various test and procedures follow before the drone fly.

1. Pre-Flight Checks: These ensure the drone is ready to fly safely.

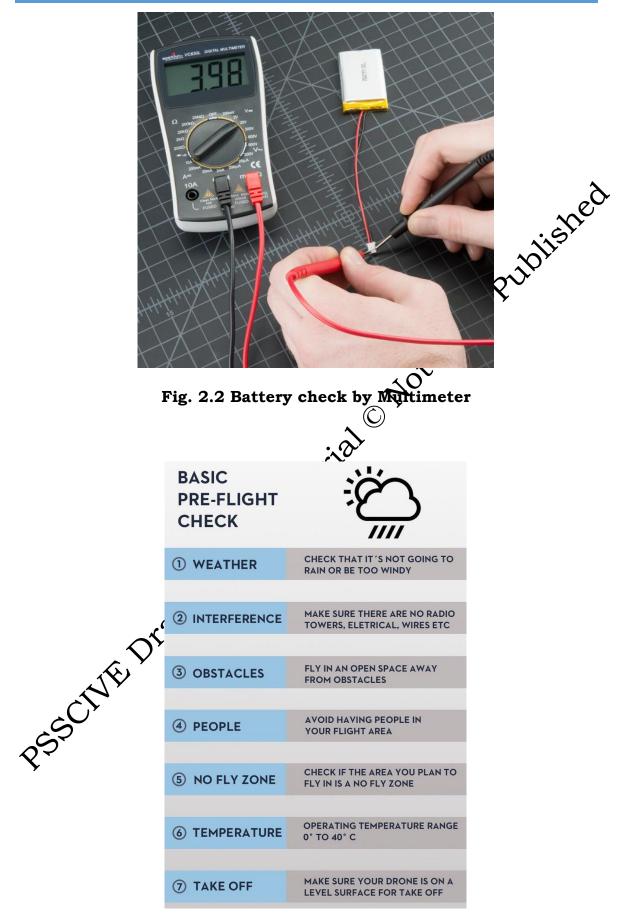
# a. Visual Inspection

In visual inspection means that check the all parts of drone damage or not? In visual inspection we follow the following steps:

- Check for physical damage (cracks, loose parts, or broken propellers). Inspect motors and propellers for wear or debris. Ensure battery is charged and securely attached. Confirm landing gear is intact. **b. Battery and Power Check:** i.
- ii.
- iii.
- iv.



#### DRONE SERVICE TECHNICIAN GRADE XII



To perform a proper battery and power check for a drone, start with a **pre-flight inspection**. Visually examine the battery for any cracks, swelling, leaks, or corrosion, and ensure that the terminals are clean and undamaged. Check that the battery is securely fitted into the drone. Next, verify the current and voltage with help of battery voltage tester or multimeter.

This can also be done on the flight app by powering on the battery and checking the LED indicator lights, ensuring it is at least 90% charged. In the drone's app, review battery health parameters such as overall capacity, individual cell voltages (which should be balanced).

Before take-off, perform a **power system check** by turning on the drone and controller in the correct sequence (Test flight), observing any error messages or LEO warnings. Spin the motors briefly to observer any unusual sources/vibration.

During the flight, continuously monitor the battery discharge rate through the flight approphealthy battery should drain gradually, not suddenly. If the power drops rapidly, land immediately and inspect the battery. Heck for overheating by monitoring the battery temperature in the app, ensuring it stays within a safe range (15°C-45°C). Avoid thing in extreme weather conditions and set low battery alerts, configuring **Return-to-Home (RTH) at 30%** and **Critical Battery**, Warning at 20% to ensure a safe landing.

After landing, allow the battery to cool down for **10-15 minutes** before echarging, avoiding direct sunlight or enclosed spaces that trap heat. Always use the **manufacturer-recommended charger** in a safe, wellventilated area, and never leave the battery unattended while charging. For long-term storage, maintain a **40%-60% charge** (storage voltage 3.7 Volt/cell) level to prevent degradation and store the battery in a fireproof Li-Po bag or in dry, cool place. Following these steps will help extend battery life, ensure flight safety, and prevent mid-air power failures. Follow the below steps for battery inspection.

- i. Confirm battery health (voltage, temperature, charge level).
- ii. Inspect battery terminals for corrosion or damage.
- Test backup batteries (if applicable). iii.

#### d. Remote Controller & Signal Test

- Check controller sticks and buttons for proper function. i.
- Published ii. Ensure stable connection between the controller and drone.
- Test video transmission quality. iii.

#### e. Environmental Check

- Assess weather conditions (wind speed, rain, temperate i.
- Verify airspace restrictions using drone digital sk ii.
- Ensure no obstacles or electromagnetic interference.(mobile tower, iii. High Tension line, transformer etc.)  $\bigcirc$

# 2. Functional and Safety Tests

These confirm the drone's core functionalities.

# a. Motor and Propeller Test

- Start motors and observe for abnormal vibrations or noises. i.
- Perform throttle respon se test. ii.
- Ensure motors roate in the correct direction.(CCW/CW) iii.

# b. GPS and Compass Calibration

- ignal strength (adequate satellites connected). i. Verity GP
- Calibrate compass in case of interference. ii.

# Sensor Test

- neck obstacle avoidance sensors.(if available)
- Test barometer and gyroscope for stable altitude hold.

#### d. Fail-Safe Mechanism Test

- Ensure Geo-fencing and Return-to-Home (RTH) function works. i.
- Test low battery warning and automatic landing system. ii.

e. Firmware and Software Check: drone's firmware and software updated is crucial for safe and efficient operation. This process ensures optimal performance, improves security, and prevents system malfunctions.

- i. Ensure the drone's firmware and software are updated.
- Verify controller and GPS calibration. ii.
- Check for any error messages on the flight app. iii.

# **3. Performance Tests**

Evaluate the drone's flight capabilities and endurance.

# a. Hovering and Stability Test

- Published Take off and hover at a low altitude to check for drift. i.
- ve Observe for sudden drops or excessive movement. ii.

# **b.** Maneuverability Test

- Test forward, backward, and sideways movement. i.
- PERFORM YAW (CW/CCW rotation), Pitch (forward and backward ii. movements) and **Roll** (right and left movements) tests.
- Execute quick directional changes to check responsiveness. iii.

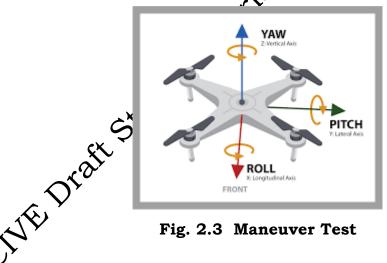


Fig. 2.3 Maneuver Test

# **Speed and Flight Time Test**

- Measure maximum speed and acceleration.
- Time-battery discharge rate under different loads. (motor thrust bench ii. test)

#### d. Camera and Gimbal Test •

- Ensure gimbal stabilization works correctly. i.
- Check camera feed for lag, distortion. ii.

iii. Test zoom, focus, and image/video recording.

# 4. Post-Flight Checks

After flight, inspect the drone to ensure it remains in good condition.

- a. Battery and Heat Inspection
- Check battery temperature and discharge rate.
- Allow batteries to cool before recharging.

## b. Data Logging and Review

- Analyze flight logs for unusual patterns or warnings.
- Download and review footage for quality assurance.

# c. Physical Inspection

- Re-examine drone for damage or inserted dust particles
- Clean drone camera lenses and propellers if necessary.

# SESSION 1: VARIOUS TESTS AND PROCEDURES FOR CHECKING

# A DRONE

# CHECK YOUR PROGRESS

## A. Fill in the Blanks

- Maintenance involves regular inspections and cleaning to prevent damage. (Routine)
- \_ health helps to avoid power failures during a 2. Checking drone flight. (Battery)
- \_\_\_\_ updates are crucial for safe and efficient 3. Firmware and drone operation. (Software)
- 4. During isual inspection, one should check for physical damage such as chacks and \_\_\_\_\_ parts. (Loose)

The battery should be charged to at least \_\_\_\_\_% before a flight. 190)

- The recommended safe temperature range for battery operation is \_\_\_\_\_ to 45°C. **(15)** 
  - 7. Setting the Return-to-Home (RTH) alert at \_\_\_\_\_% battery helps ensure a safe landing. (30)
  - 8. For long-term battery storage, maintain a charge level of \_\_\_\_\_% to prevent degradation. **(40-60)**
  - 9. During functional tests, motors should be observed for abnormal \_\_\_\_\_ or noises. (Vibrations)
- 10. Compass calibration is necessary in case of \_\_\_\_\_. (Interference)

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#### **B. Multiple Choice Questions**

- 1. Which type of maintenance focuses on preventing potential issues before they occur?
  - a) Routine Maintenance
  - b) Corrective Maintenance

- 2. What should be done first during a pre-flight check?

- Lang a pre-flight check? Hubitshed Lanbration , reeform a motor test c) Visual inspection for physical damage of d) Test video transmission quality What is the recommended st-) 3.2 3. What is the recommended storage value for a Li-PO battery? estudy Mater

  - b) 2.5
  - c) 3.7

d) 4.2

you check for during a battery and power check? 4. What she

# ry voltage and temperature

ontroller calibration

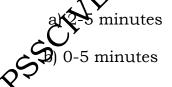
- **Compass** interference
  - d) Camera stabilization
- 5. Which test confirms that motors rotate in the correct direction?
  - a) GPS Test

## b) Motor and Propeller Test

- c) Hovering Test
- d) Sensor Test
- 6. What does the Fail-Safe Mechanism Test verify?
  - a) Stable altitude hold
  - b) Flight time and battery discharge rate

- a) Gimbal stabilization
  b) 15°C to 45°C
  c) 30°C to 60°C
  d) 50°C to 80°C
  e) Maneuverability Test
  b) Performance Test
  c) Stability Test
  d) Sensor Testx

- 9. How long ould you allow the battery to cool down before recharging



- c) 10-15 minutes
- d) 20-30 minutes

# **C. Short Answer Questions**

- 1. What is the purpose of a visual inspection before a drone flight?
- 2. Why is battery health inspection important for drones?

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#### DRONE SERVICE TECHNICIAN GRADE XII

- 3. What steps should be followed to perform a proper battery check?
- 4. Explain the purpose of the Return-to-Home (RTH) feature.
- 5. How does firmware updating improve drone performance?
- 6. Describe the process for checking the stability of a drone during flight.
- 7. What environmental factors should be assessed before flying a drone?
- 8. Why should the battery be allowed to cool before recharging?

9. What is the role of the GPS and compass calibration test? 10. How can flight logs help improve drone performance and safety the public test of the GPS and compass calibration test?

# SESSION 2: TROUBLESHOOTING METHODS FOR VARIOUS TYPES OF DRONES.

# **Troubleshooting Methods for Various Types of Drones:**

Drones can experience a range of issues, including power failures, connectivity problems, flight instability, or sensor malfunctions. Effective troubleshooting depends on identifying the type of drone and the nature of the problem. Below are common troubleshooting methods for various types of drones, including consumer, FPV, professional, and industrial depends.

ver

# 1. General Troubleshooting for All Drones

## A. if Drone is not Arming

- ✓ Ensure the battery is fully charged and properly inserted.
- ✓ Check battery connectors for dirt, corrosic or loose contacts.
- ✓ Try using a different battery if availabl€
- $\checkmark$  If the battery is swollen or damaged preplace it immediately.

# B. Controller Not Connecting to Drope

- $\checkmark$  Restart both the drone and the controller.
- ✓ Ensure the controller and drone firmware are updated.
- ✓ Try re-pairing the controller with the drone using the manufacturer's instructions.
- ✓ Check if there is signal interference from nearby electronics.
- $\checkmark\,$  Reset the tione to factory settings if necessary.

# C. Drone Won't Take Off

- Ensure the all propellers are correctly attached right direction and oright position.
- Calibrate the IMU (Inertial Measurement Unit) and Compass.
  - $\checkmark$  Check for any error messages in the flight app.
  - $\checkmark$  Ensure the takeoff location is free from magnetic interference.

# D. Drone is Drifting or Unstable in Flight

- $\checkmark\,$  Recalibrate the IMU, compass, and gyroscope through the app.
- $\checkmark$  Check for damaged propellers and replace them if necessary.
- ✓ Fly in an open area with strong GPS signal to prevent interference.

✓ Inspect the motor and ESC (Electronic Speed Controller) for any loose connections.

# 2. Troubleshooting FPV (First-Person View) Drones

# A. Poor Video Transmission or Black Screen

- ✓ Check the VTX (Video Transmitter) antenna for damage or improper installation. be Published
- ✓ Change to a different FPV channel to avoid interference.
- ✓ Ensure the FPV goggles/receiver firmware is up to date.
- ✓ Test with another camera or video transmitter if possible.

# **B.** Unresponsive Controls (Lag or Delay)

- $\checkmark$  Ensure the radio transmitter signal is strong.
- ✓ Try changing the radio frequency channel.
- ✓ Check if the receiver is properly bound to the transmitter.
- $\checkmark$  Reduce video transmission power to average interference with control signals.  $(\mathbb{C})$

# 3. Troubleshooting Consumer & Professional Camera Drones (DJI, Autel, Parrot, etc.)

- ✓ Gimbal is Shaky or Not Lev€
- $\checkmark$  Calibrate the gimbal through the flight app.
- ✓ Check for loose gimba connectors.
- $\checkmark$  Restart the dron Grid update the firmware.
- $\checkmark$  Avoid flying in strong wind as it affects gimbal stability.

# B. GPS Signal Weak or Not Locking

✓ Ensute the drone is in an open outdoor area away from tall buildings and power lines.

ait until drone GPS connects with at least 10-12 satellites before taking off.(Sat-Counts)

- ✓ Restart the drone and allow it to re-acquire GPS.
- ✓ If indoors, switch to ATTI (Attitude) mode to fly manually.

# 4. Troubleshooting Industrial & Delivery Drones

# A. Battery Not Holding Charge

 $\checkmark$  Check the battery cycle count (batteries degrade after ~200-300 cycles).

- $\checkmark$  Ensure batteries are stored properly at 40%-60% charge when not in use.
- $\checkmark$  If using a swappable battery system, ensure the connectors are clean and undamaged.

# B. Payload Integration Issues (e.g., Camera, Sensors, LiDAR Not Working)

- $\checkmark$  Check for loose or disconnected payload cables.
- $\checkmark$  Ensure the drone firmware supports the specific payload.
- $\checkmark$  Restart the drone and reinitialize the payload.
- ✓ If using third-party software, ensure compatibility rope flight system.

# 5. Common Drone Software & App Issues

# A. App Not Connecting to the Drone

- $\checkmark$  Restart the mobile device and re-launch the
- $\checkmark$  Ensure the drone's firmware and app  $\frac{1}{100}$  both up to date.
- $\checkmark$  Clear the app cache or reinstall the pp if issues persist.
- ✓ Check if the drone is in Wight or RC mode, depending on the connection method.

# B. Firmware Update Fails or Fr

- ✓ Always install latest firmware from manufacturers websites.
- $\checkmark$  Ensure the batter is above 50% before updating.
- ✓ Use a stable internet connection.
- Try updating via a computer using USB if OTA (Over-the-Air) updates

pdate gets stuck, restart the drone and try again.

# SESSION 2: TROUBLESHOOTING METHODS FOR VARIOUS TYPES OF DRONES.

# **CHECK YOUR PROGRESS**

## A. Fill in the Blanks

- 2. To reconnect a drone controller, ensure the firmware (updated)
- 3. If a drone drifts during flight, \_\_\_\_\_ the IMU compass, and gyroscope. (recalibrate)
- 4. For improved FPV video transmission, check the \_\_\_\_\_ antenna for damage. (VTX)
- 5. To stabilize a shaky gimbal, \_\_\_\_\_ the gimbal through the flight app. (calibrate)
- 7. When troubleshooting battery issues, check the battery \_\_\_\_\_ count.
- 8. To resolve app connection problems, clear the app \_\_\_\_\_ or reinstall it. (cache)
- 9. If a firmware update fails, try updating via a computer using \_\_\_\_\_.
- 10. To woid interference with control signals, reduce video transmission . (power)

# **B. Multiple Choice Questions**

- 1. What should you do if a drone won't turn on?
  - a) Replace the propellers

## b) Check battery connectors for dirt or corrosion

c) Increase video transmission power

- d) Fly in an open area
- 2. What should you check if your controller is not connecting to the drone? a) Battery cycle count
  - b) IMU calibration

# c) Firmware updates

- 3. Which component should be calibrated to address unstable dratter flight?
  a) Gimbal
  b) Compass
  c) Payload system
  d) Battery
  4. What action should be the total of the tota

- 4. What action should be taken if your RPV poor? drone's video transmission is
  - a) Change the propeller direc
  - b) Update the gimbal fir
  - c) Switch to a different FPV channel
  - d) Use ATTI mo
- gnal interference in FPV drones, you should: 5. To pre

# ease video transmission power

ncrease battery charge level

- Calibrate the IMU
  - d) Replace the ESC
- 6. What should you do if the gimbal is shaky or not level?
  - a) Fly the drone indoors

## b) Calibrate the gimbal through the flight app

- c) Restart the mobile device
- d) Increase video transmission power
- 7. What is recommended if the GPS signal is weak?
  - a) Wait for 5 satellites
  - b) Move near tall buildings

# c) Restart the drone and wait for 10-12 satellites

- d) Clear the app cache
- dished 8. What is a common reason for industrial drone batterie aling to hold ot to be charge?
  - a) Overuse of the ESC
  - b) Damaged VTX antenna

# c) Battery degradation after multiple

- d) Signal interference
- 9. Which action can help if a payload sensor isn't working?
  - a) Replace the motor
  - b) Ensure compatibility with the drone's flight system
  - c) Increase video transmission power
  - mode d) Fly in
- a recommended action if a firmware update fails? 10. Wha
  - y the drone in a different location
- b) Perform an IMU calibration

# c) Use a stable internet connection and try updating via USB

d) Replace the GPS module

# **C. Short Answer Questions**

- 1. What should you do if a drone's battery connectors are corroded?
- 2. How can you resolve a controller that fails to connect to the drone?

#### DRONE SERVICE TECHNICIAN GRADE XII

- 3. What steps should you take if your drone is drifting during flight?
- 4. How can you fix poor video transmission on an FPV drone?
- 5. What troubleshooting steps are recommended for a shaky gimbal?
- 6. What is the recommended number of GPS satellites for stable drone operation?
- 7. How can you prevent battery issues in industrial drones?
- 8. What steps should you take if a payload device is not responding?  $\lambda$
- 8. What steps should you take if a payload device is not responding?
  9. What actions can you take to troubleshoot an app that won't spheret to the drone?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?
  10. What precaution should be taken before performing a firmware update?

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#### **SESSION 3: DRONE LIFE CYCLE MANAGEMENT**

Drone Life Cycle Management: Drone Life Cycle Management (DLCM) refers to the systematic process of managing a drone from its acquisition to retirement. This involves planning, its procurement, deployment, maintenance, upgrades, and disposal. Proper life cycle management ensures optimal performance, cost-efficiency, regulatory compliance, and valety throughout the drone's operational life. Importance of Drone Life Cycle Management:

Proper drone management prevents failures, extends lifespan, and ensures drones operate safely within legal guidelines. Organizations using drones for commercial, industrial, or defence application benefit from structured DLCM by reducing downtime, optimizing costs, and enhancing data security.

Phases of Drone Life Cycle Managemen

- 1. Planning and Procuremen
- 2. Deployment and Ope
- 3. Maintenance and Troubleshooting
- Performance Optimization 4. Upgrades and
- 5. Decommissioning and Disposal
- ing and Procurement: Before acquiring a drone, users must assess 1. Plan perational needs, budget constraints, and regulatory requirements. Selection factors include payload capacity, battery life, range, and software compatibility. After purchase, drones must be registered with aviation authorities such as the FAA, EASA, or DGCA, depending on the region.
- **2. Deployment and Operations:** Once a drone is procured, it must undergo setup and configuration, including firmware updates, calibration, and

safety checks. Pilots must follow pre-flight and post-flight checklists to ensure safe operations. Fleet management systems can assist in tracking drone usage, battery life, and software updates.

#### 3. Maintenance and Troubleshooting

Regular maintenance prevents failures and extends the drone's lifespan. This includes:

Checking battery health and charging cycles Inspecting properties, motors, and sensors, Updating firmware and software for security and performance improvements Common issues like connectivity loss, unstable flight, or camera malfunctions require troubleshooting and, in some cases, part replacements.

- 4. Upgrades and Performance Optimization: As technology evolves, drones can be upgraded with better sensors, enhanced AI-driven software, and longer-lasting batteries. Organizations must assess whether upgrading is more cost-effective than purchasing a new drone.
- 5. **Decommissioning and Disposal:** When a drone reaches the end of its operational life, it must be retired safely. Components such as batteries motors, and electronic parts should be recycled or disposed of following environmental regulations. Organizations should implement proper data-wiping protocols before disposal to protect gensitive information.

Drone Life Cycle Management ensures the safe, efficient, and costeffective operation of drones. By following a structured approach, organizations can maximize the performance and longevity of their drones while maintaining compliance and minimizing environmental impact.

# **SESSION 3: DRONE LIFE CYCLE MANAGEMENT**

#### **CHECK YOUR PROGRESS**

#### A. Fill in the Blanks

- 1. Drone Life Cycle Management (DLCM) refers to the systematic process of managing a drone from its \_\_\_\_\_ to its retirement. (acquisition)
- Proper DLCM ensures optimal performance, cost-efficiency, regulatory compliance, and \_\_\_\_\_ throughout the drone's operational life. (safety)
- 3. The first phase of Drone Life Cycle Management is \_\_\_\_\_ and procurement. (planning)
- 4. Drones must be registered with aviation suthorities such as the \_\_\_\_\_, EASA, or DGCA. (FAA)
- 5. Fleet management systems help track drone usage, battery life, and \_\_\_\_\_ updates. (software)
- 6. Regular maintenance includes checking battery health, inspecting propellers, and updating . (firmware)
- 7. Common issues such as connectivity loss and unstable flight may require \_\_\_\_\_. (treubleshooting)
- 8. Drones can be upgraded with better sensors, enhanced AI-driven software, an thorner-lasting \_\_\_\_\_. (batteries)
- 9. Drone barteries and electronic components should be recycled following \_\_\_\_\_ regulations. (environmental)
- 10. Froper data-wiping protocols should be implemented before \_\_\_\_\_\_ to protect sensitive information. (disposal)

#### **B. Multiple Choice Questions**

- Which of the following is NOT a phase in Drone Life Cycle Management? a) Planning and Procurement
   b) Deployment and Operations
  - c) Storage and Packaging
  - d) Maintenance and Troubleshooting

#### DRONE SERVICE TECHNICIAN GRADE XII

- 2. What is the primary goal of Drone Life Cycle Management (DLCM)?
  - a) Maximizing drone flight speed
  - b) Ensuring safe, efficient, and cost-effective drone operation
  - c) Reducing drone size and weight
  - d) Increasing drone camera resolution
- 3. Before purchasing a drone, organizations should assess their \_ lished a) Skill level in photography
  - b) Budget constraints and operational needs
  - c) Storage capacity for video files
  - d) Social media presence
- .. in be Not to be 4. Which authority is responsible for drone registration in the United States? States?
  - a) FAA
  - b) EASA
  - c) DGCA
  - d) NASA
- 5. Which system helps in tracking direct usage and software updates?
  - a) Drone Radar System
  - b) Fleet Management Sys
  - c) Air Traffic Control
  - d) Drone Positioning
- 6. Regular main to hance of a drone involves:
  - a) Changing the propeller design
  - b) Checking battery health and updating firmware
  - c) Upgrading motors every month
  - Cleaning the camera lens only

Which component is commonly upgraded to improve drone performance? a) Battery

- b) Propeller guard
- c) Landing gear
- d) Carrying case
- 8. What is the purpose of decommissioning a drone?
  - a) To increase battery performance
  - b) To safely retire the drone and dispose of its components

#### DRONE SERVICE TECHNICIAN GRADE XII

- c) To increase flight range
- d) To improve camera clarity
- 9. Which process ensures data security before disposing of a drone?
  - a) Data encryption
  - b) Firmware rollback
  - c) Data-wiping protocols
  - d) Hardware recalibration
- 10. Which of the following is NOT part of regular drone maintenant. Checking battery health
   b) Inspecting propellers and motors
   c) Updating camera resolution
   d) Updating firmware and software

# **C. Short Answer Questions**

- 1. What is the primary purpose of the Life Cycle Management (DLCM)?
- 2. Name the five phases of Drone Late Cycle Management.
- 3. Why is proper planning important before purchasing a drone?
- 4. Which regulatory authorities are responsible for drone registration in different regions?
- 5. What role do flection an agement systems play in drone operations?
- 6. List two composite maintenance practices for drones.
- may arise if a drone is not maintained properly? 7. What issue
- 8. How an drone performance be optimized through upgrades?
- is it essential to implement data-wiping protocols before drone posal?
- What environmental considerations should organizations follow during drone disposal?

# SESSION 4: VARIOUS FORMATS PREPARE DURING REPAIR AND MAINTENANCE OF DRONE

Drones are complex machines that require regular maintenance and precise repairs to ensure optimal performance and safety. Using various formats for documentation during repair and maintenance is essential for several reasons:  $\delta$ 

# 1. Ensuring Systematic Maintenance & Repairs

- Different formats like checklists, reports, and logs help of ure that all maintenance steps are followed systematically.
- Reduces the risk of missing critical inspections, such as battery health, propeller condition, or GPS calibration.

# 2. Improving Safety & Reliability

- Incident reports track drone failores and help identify recurring issues.
- Flight test logs verify that the arone is functioning properly before use.
- Helps prevent accidents due to undetected mechanical or software issues.

# 3. Efficient Troubleshooting & Diagnosis

- Repair reports provide a history of previous fixes, making it easier to diagnose new issues.
- Heips technicians quickly identify whether an issue is a one-time failure or a persistent problem.

## 4. Reducing Downtime & Operational Delays

- Preventive maintenance schedules ensure drones are serviced at regular intervals, preventing unexpected failures.
- Parts inventory logs help track spare parts, ensuring quick repairs without waiting for replacements.

# 5. Cost Management & Budgeting

- Repair cost estimates help plan expenses and optimize budgets.
- Maintains transparency in repair expenses for stakeholders and drone operators.
- Helps compare maintenance costs across different drones and models.

# 6. Compliance & Regulatory Requirements

- Many industries and governments require maintenance records for legal and safety compliance.
- Proper documentation helps in insurance claims in case of accidents.
- Ensures drones meet aviation and safety spandards before deployment.

# 7. Performance Tracking & Optimization

- Flight test logs track drone performance over time, identifying potential issues early.
- Battery cycle reports ensure batteries are replaced before they degrade, improving efficient
- Helps in making data-driven decisions on drone upgrades or replacements

Using various formats during drone repair and maintenance is crucial for safety, efficiency, cost control, and compliance. Proper documentation ensures smooth operations, reduced downtime, and long-term reliability of drones.

Some arious formats during drone repair and maintenance shown in below

#### DRONE SERVICE TECHNICIAN GRADE XII

## **Drone Maintenance Checklist:**

S.no.	Date	Drone ID	Task	Status ( ✔/¥)	Remarks
1.	2025-02-17	D12345	Battery Health Check	~	No issues found
2.	2025-02-17	D67890	Propeller Inspection	*	Minor cracks detected
3.	2025-02-17	D34567	Firmware Update	~	Version 1.3 installed
4.	2025-02-17	D12345	Battery Health Check		<b>N</b> o issues found
5.	•••••	•••••		·····	
6.		•••••	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	ç	
7.	•••••	•••••		•••••	
8.		•••••		•••••	
9.	•••••			•••••	

Above check list Helps technicians systematically check and mark leted tasks. e Repair Report: completed tasks.



# Drone Repair Report:

S.no.	Drone	Repair	Issue	Repairs	Technician	Parts	Cost
	ID	Date	Reported	Done	Name	Used	
1.	M12345	2025- 02-17	GPS Malfunction	Replaced GPS module	John Doe	GPS Module	•••••
2.			•••••	•••••			
3.			•••••	•••••			
₹₽`	•••••		•••••	•••••			
5.	•••••	•••••	•••••	•••••	•••••		
6.		•••••			••••		

Above check list Tracks all repairs and helps in budgeting maintenance costs.

# Session 4: Various Formats Prepare During Repair and

# Maintenance of Drone

# **CHECK YOUR PROGRESS**

#### A. Fill in the Blanks

- 1. Different formats like \_\_\_\_\_, \_\_\_\_, and logs ensure and log
- 2. \_\_\_\_\_ reports drone failures and helps identify recurring sizes. (Incident)
- 3. \_\_\_\_\_ logs verify that the drone is functioning properly before use. (Flight test)
- 4. \_\_\_\_\_ reports provide a history of previous fixes, naking it easier to diagnose new issues. (Answer: Repair)
- 5. Preventive maintenance schedules ensure drates are serviced at \_\_\_\_\_\_\_ intervals. (Answer: regular)
- 6. Parts \_\_\_\_\_ logs help track spare parts or quick repairs. (Answer: inventory)
- 7. Repair cost estimates help plan expenses and optimize \_\_\_\_\_. (Answer: budgets)
- 8. Many industries and governments require maintenance records for \_\_\_\_\_ compliance. (Answer: ) (Cal and safety)
- 9. Proper documentation helps in case of accidents. (Answer: insurance)
- 10. Battery \_\_\_\_\_ reports énsure batteries are replaced before they degrade. (Answer: cycle)

# B. Multiple Choice Questions

1. Which of the blowing formats ensures systematic maintenance steps are followed?



- d) Advertisements
- 2. What type of reports track drone failures and identify recurring issues? a) Flight logs

## b) Incident reports

c) Repair logs

- d) Inventory logs
- 3. Which documentation helps identify whether an issue is a one-time failure or a persistent problem?
  - a) Incident reports
  - b) Flight logs

- a) Budget sheets
  4. Which log helps verify that a drone is functioning properly before deployment?
  a) Maintenance schedule
  b) Incident report
  c) Flight test log
  d) Repair report
  5. What ensures drones are service dat regular intervals?
  a) Maintenance schedule Mathematical and the service dat regular intervals?
  b) Repair cost sheet Mathematical and the service data service data

- c) Budgeting rep
- d) Flight log
- 6. Which downent helps track spare parts for quick repairs? dent report

# Parts inventory log

- c) Repair report
- d) Maintenance schedule
- 7. Which report helps plan expenses and optimize budgets?
  - a) Incident report

#### b) Repair cost estimate

- c) Maintenance schedule
- d) Flight test log (Answer: b)
- 8. Which type of documentation supports insurance claims in case of accidents?
  - a) Budget report

- 9. Battery cycle reports are essential to ensure

- . eports are essential to ensure \_\_\_\_\_\_ be publicated a) Budget control b) Battery replacement before degradation c) Efficient spare parts usage i) Inventory control /hich of the following is essential to andards? a) Incident reproducts 10. Which of the following is essented

  - c) Maintenance
  - d) Budget s

#### C. Short Answe Questions

- s it important to use different formats like checklists and logs in one maintenance?
- How do incident reports improve the safety and reliability of drones?
  - 3. What is the purpose of flight test logs in drone maintenance?
- 4. How do repair reports help in diagnosing new issues?
- 5. What role do preventive maintenance schedules play in reducing downtime?
- 6. How does a parts inventory log contribute to efficient repairs?
- 7. Why are repair cost estimates important for budget management?

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- 8. How can proper documentation assist in insurance claims?
- 9. What is the significance of battery cycle reports in drone maintenance?
- 10. How does maintaining proper records ensure compliance with regulatory requirements?

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## **MODULE 3**

## OPPORTUNITIES, RULES AND REGULATIONS

#### Module Overview

In this Module, students will explore the vast opportunities and regulatory landscape of the drone industry. The first session introduces various career prospects in the rapidly growing drone sector, highlighting roles in areas such as aerial photography, agriculture, logistics, surveillance, and disaster management. It provides insights into the skills and qualifications required to build a successful career in this field. The second session focuses on drone regulations in India, outlining the legal framework governing crone operations.

Students will learn about licensing requirements, airspace classifications, safety guidelines, and compliance measures set by regulatory authorities. By the end of this module, learners will gain a comprehensive understanding of both the career potential and the legal responsibilities associated with the drone industry.

## Learning Outcomes

After completing this module, you will be able to:

- Understand various career opportunities available in the drone industry.
- Identify the skills and qualifications required for different roles in the drone sector.
- Explore the potential solutions of drones in different industries.
- Gain knowledge of the current drone regulations in India.
- Understand the legal and safety requirements for operating drones in India.
- Learn about the necessary permits, licenses, and compliance measures for drone usage.
- Recognize the importance of regulatory frameworks in ensuring safe and responsible drone operations.

#### **Module Structure**

**Ossion** 1: Career in the drone industry

Session 2: Drone Regulations in India

The drone sector presents a wealth of opportunities across various industries, including precision agriculture, construction, energy, transportation, film, and research. Drones can revolutionize tasks like crop monitoring, site surveying, infrastructure inspection, package delivery, and data collection, while also contributing to advancements in film production, real estate marketing, and scientific research. As drone technology continues to evolve, new applications and industries are likely to the research further expanding the sector's potential.

## SESSION 1: CAREER IN THE DRONE INDUSTRY

The drone industry is rapidly expanding, offering a diverse range of career paths for individuals with a passion for technology, innovation, and aviation.

#### **Key Career Paths:**

• **Drone Pilot:** Operate drones for perial photography, videography, inspections, deliveries, and other applications.

Requirements:

- Remote Pilot Certificate from DGCA authorized RPTO (Remote Flot).
- Strong understanding of flight regulations and safety procools issued by DGCA.
- Sexcellent hand-eye coordination and spatial awareness
- **Drone Engineer:** Who Design and develop complete product, drones and their components.

pecializations:

- Aeronautical Engineering: Focus on aerodynamics, flight mechanics, and structural design.
- Mechanical Engineering: Design and build drone components like motors, propellers, and frames.
- Electrical Engineering: Develop and integrate electronics, sensors, and communication systems.

- Software Engineering: Develop flight control software, data processing algorithms, and autonomous flight capabilities.
- **Drone Data Analyst:** Collect, analyze, and interpret data captured by drones.

Applications:

- Agriculture: Crop health monitoring, yield prediction  $\lambda$
- Construction: Site surveying, progress tracking  $\propto$
- Environmental: Wildlife monitoring, disaster response
- Drone Technician: Perform maintenance, repairs, and in spections on drones.
- **Drone Instructor**: Train aspiring drone pilots and technicians.
- Drone Entrepreneur: Start a drone-based business, such as aerial photography services, drone delivery, or dealer data analysis.

#### **Education and Training:**

- **Degrees/Diploma:** Diploma/Bachelor's or Master's degrees in engineering, computer science, aviation, or related fields.
- Certifications: Remote Pilot Certificate, industry-specific certifications (e.g., precision agriculture, construction inspection).
- Training Programe Online courses, workshops, and hands-on training programs offered by universities, flight schools, and industry organizations.

#### Skills:

- **Technical Skills:** Proficiency in drone operation, data analysis, software programming, and electronics.
- **Soft Skills:** Problem-solving, communication, teamwork, customer service, and a strong work ethic.

#### **Industry Trends:**

 Advancements in AI and Autonomy: Increasing use of artificial intelligence and machine learning for autonomous flight and data analysis.

- Integration with Other Technologies: Integration of drones with other technologies such as the Internet of Things (IoT), 5G networks.
- Growth of Drone Delivery: Expansion of drone delivery services for ecommerce, medical supplies, and other goods.

## **Opportunities:**

The drone industry offers exciting career opportunities with competitive salaries and the potential for significant growth. As the technology contines to evolve, the demand for skilled professionals in this field will only increase. This session provides a brief overview of the diverse career paths available in the drone industry. Further research and exploration are provouraged to make informed career decisions.

SESSION 1: CAREER IN THE ORÓNE INDUSTRY

# CHECK YOUR PROGRESS

### A. Fill in the Blanks

- 1. A certified drone pilot must obtain the \_\_\_\_\_ certificate. (Remote Pilot Certificate)
- 2. A \_\_\_\_\_\_ or gineer focuses on designing drone components such as motors, propellers, and frames. (Mechanical)
- 3. Drones are increasingly integrated with technologies like the Internet of Naings (IoT) and \_\_\_\_\_\_ networks. (5G)

specialises in analyzing data collected by drones for

applications like agriculture and construction. (Drone Data Analyst)

5. The growing trend in the drone industry includes the expansion of

\_\_\_\_\_ services for e-commerce and medical supplies. (Drone

### **Delivery**)

6. A \_\_\_\_\_\_ operates drones for aerial photography, inspections, and deliveries. (Drone Pilot)

- 7. A \_\_\_\_\_\_ designs, develops, and maintains drones and their components. (Drone Engineer)
- 8. \_\_\_\_\_\_ engineering focuses on aerodynamics, flight mechanics, and structural design. (Aeronautical)
- 9. The application of drone data analysis in agriculture includes \_\_\_\_\_ and yield prediction. (Crop health monitoring)

#### **B.** Multiple Choice Questions (MCQs)

- 10. A \_\_\_\_\_\_ trains aspiring drone pilots and technicians. (Drone Instructor)
  Multiple Choice Questions (MCQs)
  1. What certification is required to operate a drone compercially in the India ?

  a) FAA Part 102
  b) DGCA Remote Pilot License
  c) Drone Operation Permit
  e) FAA Part 107

  2. Which specialization focuses on developing flight control software for drones? drones?
  - a) Aeronautical Engineering
  - b) Mechanical ngineering
  - c) Software Engineering
  - Anical Engineering
  - hich career path involves maintaining and repairing drones?
  - a) Drone Pilot
    - b) Drone Instructor
    - c) Drone Technician
    - d) Drone Data Analyst
  - 4. Which sector commonly uses drones for crop health monitoring and yield prediction?

- a) Construction
- b) Agriculture
- c) Environmental Research
- d) Transportation
- 5. Which skill is crucial for a drone pilot?

- ung skills ung sk

- - b) Drone Entrep
  - c) Drone Tec
  - d) Drone eineer
- industry trend emphasizes AI for autonomous flight and data alvsis?
  - a) Integration with 5G networks
    - b) Growth of drone delivery

#### c) Advancements in AI and Autonomy

- d) Enhanced customer service programs
- 9. What type of engineer designs drone flight mechanics and structural design?

- a) Electrical Engineer
- b) Mechanical Engineer

#### c) Aeronautical Engineer

- d) Civil Engineer
- 10. Which of the following skills is considered a soft skill in the drone X to be Published

industry?

- a) Programming
- b) Electronics troubleshooting
- c) Communication
- d) Data analysis

#### **C. Short Answer Questions**

- 1. What are the key responsibilities of a drop pilot?
- 2. Explain the role of a Drone Data Analyst in the agriculture industry.
- 3. What are the primary differences between a Drone Engineer and a Drone Technician?
- 4. Describe the educational pathways required to become a drone engineer.
- distry trends driving the growth of the drone 5. What are some key in sector?
- 6. How does AI explance the capabilities of modern drones?
- 7. What roles IoT play in drone technology integration?
- 8. Identic three soft skills essential for success in the drone industry.
- What certifications are important for someone aspiring to become a one instructor?
- 6. How is drone delivery transforming logistics and supply chains?

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# SESSION 2: DRONE REGULATIONS IN INDIA

Unmanned aircraft systems (UAS) in andia fall into three categories first is airplane, rotorcraft and hybrid unmanned aircraft system.

The entire drone related Operations in India are regulated by **DGCA** under the **Civil Aviation Authority of India**. DGCA issued first Drone policy "Drone Rules 2021" and further Drone (Amendment) rules 2022 and Drone (Amendment) rules 2023 are published.

They are further broken into sub-categories as follows:

- Renotely piloted aircraft system (RPAS)
- Model remotely piloted aircraft system (MRPAS)
- S are also grouped into classifications.

Classifications are based on the maximum all-up weight, including payload. The classifications are as follows:

**Nano unmanned aircraft system**: These weigh less than or equal to 250 grams. You do not require permits to fly a nano except in controlled airspace. You must ensure that you do not fly any nano drone beyond 50 ft (15m) Above Ground Level (AGL).

**Micro unmanned aircraft system:** These drones weigh over 250 grams but less than or equal to 2 kilograms. No permits are required for recreational use. Commercial usage and flights in controlled airspace require.

**Small unmanned aircraft system**: These SUAS weigh more than 2 kilograms but less than or equal to 25 kilograms.

**Medium unmanned aircraft system:** The MUAS weigh more than 25 kilograms but less than or equal to 150 kilograms, and Large unmanned aircraft system weighing more than 150 kilograms. Registration is required for all but the Nano category.

**Drone Registration in India:** First, register your drone on the digital sky platform. Get a unique identification number unless exempted. Do not operate a drone without doing this first.

The Director-General keeps a record All registered unmanned aircraft systems. And that record includes the unique identification number issued. The drone operator must ensure that the drone has a valid **Type** certificate.

**Application and procedure, for drone registration India:** Make an application in Form D-2 of the digital sky platform along with the fee specified in rule 46. Provide requisite details. Include the unique number of the type certificate whe unmanned aircraft system.

The digital sky patform will verify the details. They will issue a unique identification number to the applicant. The unique identification number of a UAS is linked to its unique serial number. It is also linked to the unique serial numbers of its flight control module and remote pilot station.

Kyou change the flight control module or remote pilot station, you must update digital sky. You have to update the unique serial number of the new flight control module or remote pilot station. You have seven days after you have replaced these items. Or, you must do so before you fly the unmanned aircraft system, if earlier.

Remote Pilot Certificate in India (previously Remote Pilot License or Drone License India You can fly drones up to 2kg for non-commercial drone use without a pilot certificate (Only academic research & development purpose). All other drone uses require a Remote Pilot Certificate (RPC). The RPC must be valid and enlisted on Digital Sky.

#### **Classification:**

The RPC identifies the category, sub-category, and classification the unmanned aircraft system. It will identify combinations of these if applicable.

Q,

**Eligibility:** An individual will be eligible to get a remote pilot certificate if they- are not less than eighteen years of age and not more than sixty-five years of age have passed the class tenth examination. Or its equivalent from a recognized Board and Have completed training from any authorized remote pilot training organization.

**Procedure for obtaining a remote priot certificate:** Complete the training for your desired category, sub-category, or class. Pass the tests conducted by the authorized remote pilot training organization. Within seven days of successful completion, the training organization will apply for your RPC. They will fill in Form 9-4 on the Digital Sky platform. Pay the fee as specified in rule 46 you will be issued a remote pilot certificate through the digital sky platform. Your remote pilot certificate is issued within fifteen days.

**Note:** you are not required to get a certificate from DGCA separately after training from a DGCA-approved drone training institute. After passing the course, you will get a 'Remote Pilot Certificate' from the DGCA-approved drone training institute, making you eligible to fly micro drones for commercial purposes.

**Validity of Certificate:**A remote pilot certificate will be valid only if it is enlisted on the digital sky platform, unless suspended or canceled, remain

valid for a period of **Ten years**. Renewed for a maximum period of ten years, on payment of fee as specified in rule 46.

#### Exemption from obtaining a certificate

No remote pilot certificate will be required for operating a nano unmanned aircraft system and a micro unmanned aircraft system for non-commercial purposes.  $\searrow$ 

#### **Insurance Requirements**

The rules and laws in the Motor Vehicles Act from 1988 apply to AS. The insurance rules for paying for car accident damages also apply to drones. If a drone crashes and hurts someone or damages property, insurance will help pay for it. The rules apply in the same way they do for regular motor vehicles.

Nano unmanned aircraft systems may serate without third-party insurance. You can operate an unmanne aircraft system with special insurance for those operations. The Insurance Regulatory and Development Authority of India must approve the insurance product.

What are the requirements of the import of RPAs (with or without a camera) in India?

To import an RPAS to India, you must get Equipment Type Approval (ETA). This is obtained from WPC Wing, Department of Telecommunication. It allows for operating in a de-licensed frequency band(s). Such approval will be valid for a particular make and model.

You wast apply to DGCA along with ETA for import clearance. Based on the import clearance issued by DGCA, DGFT will issue a license to import RPAS. This does not apply to the Nano category,

Import of foreign drones is now effectively banned.

Notes for recreational drone pilots flying for fun in India

#### Drone rules India – Do's:

#### DRONE SERVICE TECHNICIAN GRADE XII

Ensure your Drone (except Nano in uncontrolled airspace up to 50ft) is Digital Sky "No Permission- No Takeoff" (NPNT) Compliant Obtain a Unique Identification Number (UIN) from DGCA for operating in controlled airspace and affix it to your drone Obtain an Unmanned Aircraft Operator Permit (UAOP), if applicable, from DGCA for commercial operations and keep it handy Obtain Permission before each flight through the Digital Sky Platform Ensure the drone is in good condition (not damaged) and fit for flying safet. Keep an eye on interference: Interference can be from mobile devices or blockage of signals, do watch out when flying your drone.

Fly only during daylight (after sunrise to before sunset) Fly in sood weather: Good weather lets you not only fly your drone better but also keep track of it in the air.

Fly in visual line of sight (VLOS): Always be within the visual range of your drone.

#### **Follow Flying Guidelines:**

Do your homework before spending considerable money on a drone.

- Make sure you clearly understand all operational and regulatory aspects.
- Be aware of Airspace Restrictions/ No Drone Zones
- Do stay away from apports and heliports
- Respect the private of people
- Keep local patie informed about your drone flying activity. If you are ever approached by police, provide all requisite information.

Do log your flights and inform concerned authorities (like DGCA, local police, etc.) of any incidents/ accidents

# Drone rules India – Don'ts:

- $\Rightarrow$  Don't fly a Nano drone above 50ft (15m) from the ground level
- $\Rightarrow$  Don't fly a Micro drone above 200ft (60m) from the ground level
- $\Rightarrow$  Don't fly drones more than 400ft (120m) from the ground level
- $\Rightarrow$  Don't fly a drone near other aircraft (manned or unmanned)
- $\Rightarrow$  Don't fly a drone near airports and heliports

- $\Rightarrow$  Don't fly a drone over groups of people, public events, or stadiums full of people without permission
- $\Rightarrow$  Don't fly the drone over government facilities/military bases or over/ near any no-drone zones.
- $\Rightarrow$  Don't fly a drone over private property unless permission is given.
- $\Rightarrow$  Don't fly a drone in controlled airspace near airports without filing a flight plan or AAI/ADC permission (at least 24 hours before actual  $\Rightarrow \text{ Don't fly a drone under the influence of drugs or alcohol the drone from a moving vehicle. ship for the drone from a moving vehicle. Ship for the drone from a moving vehicle.$

DGCA © NOL LO ation al The Directorate General of Civil Aviation the regulatory body in the field of Civil Aviation primarily dealing with safety issues. It is responsible for transport sorvices to/from/within India and for regulation of air enforcement of civil air regulations, air safety and airworthiness standards. It also co-ordinates all regulatory functions with International Civil Aviation Organisation.

#### Responsibilities of DGCA

- Atroraft Certification & Airworthiness Approves aircraft designs, ertifies airworthiness, and ensures maintenance standards.
- **Pilot Licensing & Training** Issues pilot licenses and monitors flying training institutes.
- 3. Air Safety & Accident Investigation Investigates aviation incidents and ensures compliance with safety standards.
- 4. Air Transport Regulation Approves airline operations, routes, and flight schedules.

- 5. Environmental & Consumer Protection Regulates noise pollution and passenger rights in aviation.
- 6. International Cooperation Represents India in ICAO (International Civil Aviation Organization) and other global aviation bodies.
- 7. Drone & UAV Regulation Governs the operation of drones and unmanned aerial vehicles

#### **SESSION 2: DRONE REGULATIONS IN INDIA**

#### **CHECK YOUR PROGRESS**

#### A. Fill in the Blanks

- st to be published han or equal to \_\_\_\_\_ 1. Nano unmanned aircraft systems weigh grams. (250 grams)
- 2. Micro unmanned aircraft systems wigh over 250 grams but less than or equal to \_\_\_\_\_ kilograms. (2 Gilograms)
- 3. The application for drone registration in India is made through the \_\_ platform. **(Digital Sky)**
- 4. Remote Pilot critificates are issued within \_\_\_\_\_ days after the successful completion of training. (15 days)

nport an RPAS into India, you must first obtain \_\_\_\_\_ from the VPC Wing, Department of Telecommunication. (Equipment Type Approval (ETA))

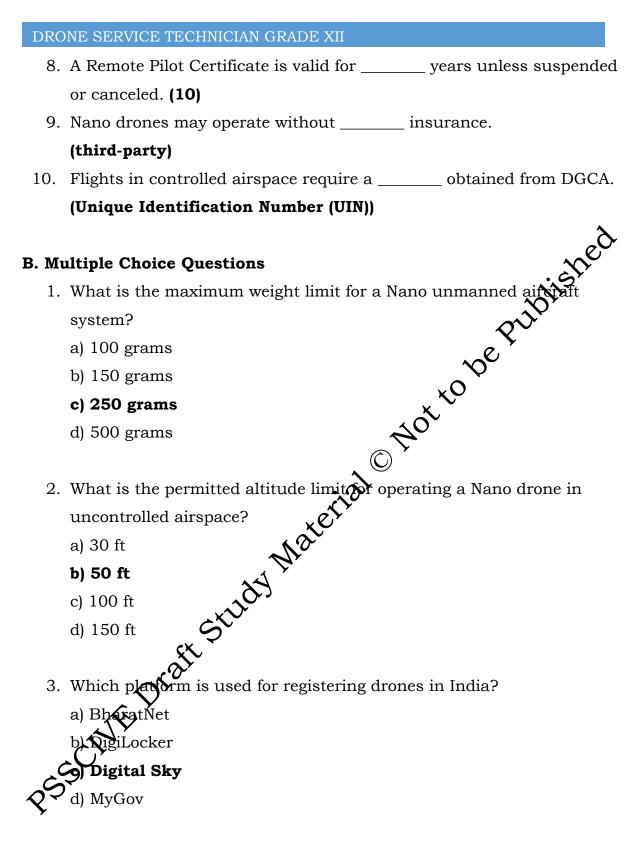
6. Unmanned Aircraft Systems (UAS) in India are categorized into

\_\_\_\_, \_\_\_\_\_, and \_\_\_\_\_\_ systems. (Airplanes, rotorcraft,

#### hybrid unmanned aircraft)

7. The unique identification number of a UAS is linked to its unique serial number and the serial numbers of its \_\_\_\_\_ and \_\_\_\_

## (Flight control module, remote pilot station)



- 4. What is the maximum altitude limit for a Micro drone for recreational use?
  - a) 50 ft
  - b) 100 ft
  - c) 200 ft

d) 400 ft

- 5. Which authority issues import clearance for RPAS in India?
  - a) DGCA
  - b) DGFT
  - c) IRDAI
  - d) WPC Wing
- 6. Which certificate is required to operate drones weighing over the commercial purposes?
  a) Remote Pilot Certificate (RPC)
  b) Drone Operation Certificate
  c) Unmanned Aircraft Operator Permit (UAOR)
  d) Drone Pilot License

- 7. What is the validity period of a Remote Pilot Certificate in India? a) 5 years b) 7 years c) 10 years d) 15 years c) What is the validity period of a Remote Pilot Certificate in India?
- 8. Which of the to owing drones requires no registration in India? a) Micro

  - no drone

Medium drone

- 9. Which category of drones requires an Unmanned Aircraft Operator Permit (UAOP) for commercial use?
  - a) Nano drones
  - b) Micro drones
  - c) Medium drones

- d) All of the above
- 10. What is the age requirement to apply for a Remote Pilot Certificate?
  - a) 16 years
  - b) 18 years
  - c) 20 years

#### **C. Short Answer Questions**

- Answer Questions
   What is the maximum altitude a Nano drone can fly in prodontrolled airspace?
   What is the registration process for a d
   What is the registration process for a d
- 3. What are the eligibility criteria for obtaining Remote Pilot Certificate?
- 4. What is the purpose of Equipment Type Approval (ETA)?
- 5. When is insurance mandatory for depres in India?
- 6. What should a drone operator **x** after replacing the flight control module or remote pilot station?
- to obtaining a Remote Pilot Certificate? 7. What is the procedure
- inform weight limit for a Small unmanned aircraft 8. What is the max system?
- ey "Do's" for drone pilots in India? 9. What are the

10. What are the key "Don'ts" for drone pilots in India?

## **MODULE 4**

## DEVELOPMENT AND INNOVATION IN DRONE TECHNOLOGY

### **Module Overview**

This unit explores the advancements and challenges in the evolving field of drone technology, with a particular focus on India's progress in this domain. The first session delves into the innovation and manufacturing capabilities of drones in India, highlighting key developments, industry growth, and emerging opportunities. It examines how technological advancements, government initiatives, and private sector involvement are shaping the dome ecosystem in the country. The second session addresses the challenges faced in drone development, including regulatory hurdles, infrastructure limitations, technological constraints, and market adoption issues.

By understanding both the progress and obstacles in the field, learners will gain valuable insights into India's journey toward becoming a global leader in drone technology.

## Learning Outcomes

After completing this module, you will be able to:

- Understand the advancements in drone technology and its significance in India.
- Analyze the innovation and manufacturing capabilities of drones in India.
- Identify key player and stakeholders in the Indian drone industry.
- Examine the challenges faced in drone development in India.
- Evaluate regulatory, technical, and economic barriers to drone innovation.
- Discuss potential solutions and future prospects for drone technology in India

### **Module Structure**

Session 1: Drone Innovation and Manufacturing Capabilities in India

Session 2: Describe the challenges regarding drone development in India

## SESSION 1: DRONE INNOVATION AND MANUFACTURING CAPABILITIES IN INDIA

India is becoming a leader in drone technology, thanks to new rules and government support. Drones are now used in many fields like farming, delivery, and disaster management. In farming, they help with tasks like checking crops and spraying pesticides. For deliveries, drones make it easier to send items to remote areas quickly. During disasters, they are used to find people, map affected areas, and deliver emergency supplies. With more investment and research, India is set to become a major player in the drone industry, creating new opportunities and progress.

## Government Initiatives Supporting Drone Innovation

The Indian government has introduced several in tatives to promote drone technology:

- **Drone Rules 2021:** Simplified the process of obtaining permissions for drone usage, reducing paper ork and restrictions.
- **Digital Sky Platform:** A platform for registering drones and obtaining necessary approvals.
- **PLI Scheme:** Financial incentives for companies involved in drone manufacturing and services.
- **Kisan Drongs:** A project aimed at providing drones to farmers to improve pricultural productivity.
- SWANNTVA YOJNA
- And one Didi: Namo Drone Didi is a central sector scheme aiming to empower women-led Self-Help Groups (SHGs) by equipping them with drone technology to provide agricultural services. The scheme aims to provide drones to 15000 selected Women SHGs during the period from 2024-25 to 2025-2026 for providing rental services to farmers for agriculture purpose (application of liquid fertilizers and pesticides for the present). This initiative is expected to generate an additional income of at least Rs. 1

lakh per year for each SHG, contributing to economic empowerment and sustainable livelihood generation.

#### Key Features of the Namo Drone Didi Scheme:

- Subsidy to Women DAY NRL-SHGs for Purchase of Drone •
- Up to 80% of Drone Cost as Subsidy upto 8 Lakhs •
- Loan facility from AIF for remaining cost of Drone
- Easy Loan @ 3% interest rate •
- Drone Pilot training as a part of Drone Package
- Chance to earn additional 1 lakh PA through Drone
- Published Renting of Drone Spray Service to Farmers through Komen SHGs

# Benefits of the Namo Drone Didi Scheme: $\chi$

- Empowerment of Women: The scheme provides specialized training in drone technology, equipping women with advanced skills that are increasingly valuable in modern agriculture. This knowledge enables them to perform tasks like crop monitoring, soil analysis, and precision farming more efficiently.
- of Agricultural Efficiency: Drone Enhancement technology • significantly enboyces the precise application of pesticides and fertilizers, transforming traditional agricultural practices. Equipped advaced GPS and sensor technology, drones can be with programmed to follow precise flight paths over fields, ensuring even and targeted application. This precision reduces the overuse of bemicals, minimizing environmental impact and lowering costs for farmers.
- Skill Development and Knowledge Expansion: The scheme provides specialized training in drone technology, enabling women to acquire advanced skills in modern agricultural practices such as applying fertilizers, pesticides, and herbicides accurately, ensuring even distribution and optimal usage. Soil and field analysis is streamlined with drones, enabling detailed surveys and fertility assessments.

#### DRONE SERVICE TECHNICIAN GRADE XII

Women can also enhance irrigation management by identifying areas needing more or less water, detecting leaks, and managing water resources efficiently.

**Community and Networking Opportunities**: Women can connect with a supportive network of fellow participants, fostering a sense of community and collaboration. They have the chance to join forums and workshops where they can share experiences, challenges, and best practices, enhancing their collective knowledge and skins The scheme also provides access to industry experts, and mentorship agricultural professionals, creating avenues for and x to De professional growth.

#### The Future of Drone Technology in India

The future of drone innovation in India looks promising. Key trends include:

- Advanced AI integration: Drones with become smarter, capable of • analyzing data in real-time.
- Swarm technology: Multipedrones working together for tasks like large-scale mapping or search-and-rescue.
- Improved battery technology: Longer flight times will increase the efficiency and race of drones.
- Expansion into new sectors: Drones will find applications in fields like health are, renewable energy, and wildlife conservation.

# Manufacturing Capabilities in India

India has emerged as a significant player in the global manufacturing sector. With its large workforce, growing technological expertise, and supportive government policies, the country has become a preferred destination for manufacturing across various industries. From traditional sectors like textiles and automotive to cutting-edge fields like electronics and aerospace, India's manufacturing capabilities are evolving rapidly. This document explores the factors driving India's manufacturing growth, key sectors, government initiatives, and future potential.

#### The Growth of Manufacturing in India

Manufacturing has always been a critical component of India's economy. With the introduction of initiatives like "**Make in India**", the sector has seen a renewed focus. India aims to increase its manufacturing contribution GDP from the current 17% to 25% by 2025. Factors contributing this growth include:

- 1. **Demographic Advantage**: India has a young and dynamic workforce, with a median age of 28 years, providing a steady supply of skilled and semi-skilled labor.
- 2. **Cost Competitiveness**: Lower labor compared to developed nations make India an attractive manufacturing hub.
- 3. Large Domestic Market: With a population of over 1.4 billion, India provides a vast consumer base for locally manufactured goods.
- 4. **Improved Infrastructure**: Significant investments in roads, railways, ports, and power have boosted manufacturing capabilities.

#### Key Manufacturing Sectors in India

#### 1. Automotive

India some of the largest producers of automobiles in the world. Key highlights include:

- Major global players like Hyundai, Toyota, and Ford have manufacturing plants in India.
- India is also a hub for two-wheelers, with companies like Bajaj Auto and Hero MotoCorp leading the market.

A growing focus on electric vehicles (EVs) is driving innovation in the • sector.

### 2. Textiles and Apparel

The textile industry is one of the oldest and largest in India, contributing significantly to exports. Key factors include:

- Availability of raw materials like cotton, jute, and silk.
- A skilled workforce with expertise in spinning, weaving, manufacturing.
- Growth in technical textiles, used in industries like healthcare and automotive. • 4°××°

### **3. Electronics**

India is rapidly growing its electronics manufacturing capabilities. Key developments include:

- · Growth in smartphone production, with companies like Samsung, Xiaomi, and Apple setting up manufacturing units.
- Expansion in consu electronics, semiconductors, and electronic components.
- The PLI Sche for Electronics has incentivized local production.

# 4. Pharmaceut

known as the "Pharmacy of the World" due to its robust India aceutical manufacturing sector. Key points include: phar

- Leading in the production of generic medicines and vaccines.
- Home to world-class manufacturing facilities adhering to global standards.
- A significant contributor to COVID-19 vaccine production.

### 5. Aerospace and Defence

The aerospace and defence sector is gaining momentum with increased domestic production. Highlights include:

- Partnerships with global defence companies to manufacture aircraft, drones, and military equipment.
- Government initiatives promoting self-reliance, such as "Atmanirbhar Bharat".

#### **Government Initiatives Supporting Manufacturing**

- 1. **Make in India**: Launched in 2014, this initiative aims to position India as a global manufacturing hub by attracting investments and simplifying regulations.
- Production-Linked Incentive (PLI) Scheme: Provides financial incentives for manufacturers in textiles.
- 3. **Skill India**: Focuses on upskilling the workforce to meet the demands of advanced manufacturing technologies.
- 4. **Industrial Corridors**: Development of industrial corridors like the Delhi-Mumbai Industrial Corridor (DMIC) to improve connectivity and boost manufacturing
- 5. **Ease of Doing Dusiness**: Reforms in taxation, labour laws, and licensing to create a business-friendly environment.

## Challenges in Indian Manufacturing

Despite significant progress, there are challenges that hinder the full potential of India's manufacturing sector:

- 1. **Infrastructure Gaps**: While improving, infrastructure in some regions still needs further development.
- 2. **Technological Lag**: Adoption of advanced manufacturing technologies like automation and AI is limited.
- 3. **Skilled Workforce**: A need for more trained professionals in high-tech manufacturing.

4. **Complex Regulations**: Although improving, regulatory processes can still be cumbersome in certain sectors.

#### The Future of Manufacturing in India

The future of manufacturing in India looks promising, with several trends shaping its trajectory:

- 1. **Digital Transformation**: Increasing adoption of Industry 4.0 technologies like IoT, robotics, and AI.
- 2. Green Manufacturing: A shift towards sustainable practices and renewable energy.
- 3. **Global Supply Chain Integration**: India is becoming a preferred alternative to China in global supply chains.
- 4. Focus on R&D: Increased investments is research and development to boost innovation.
- 5. **Expansion of MSMEs**: The growth of Micro, Small, and Medium Enterprises (MSMEs) will drive boalized manufacturing.

India's manufacturing sector is on the cusp of a transformation. With a young workforce, supporting government policies, and advancements in technology, the country has the potential to become a global manufacturing powerhouse. Addressing existing challenges and fostering innovation will ensure that India achieves its ambitious goals, creating jobs, boosting exports, and driving economic growth.

# SESSION 1: DRONE INNOVATION AND MANUFACTURING CAPABILITIES IN INDIA

#### **CHECK YOUR PROGRESS**

#### A. Fill in the Blanks

- The Indian government introduced the \_\_\_\_\_\_ in 2021 to simply the process of obtaining permissions for drone usage. (Drone Rules 2021)
- 2. The \_\_\_\_\_\_ platform is used for registering drones and obtaining necessary approvals. (Digital Sky)
- 3. Under the Namo Drone Didi scheme, 80% of the trone cost is provided as a subsidy up to \_\_\_\_\_ lakh. (8)
- 4. India's manufacturing sector aims to increase its GDP contribution from the current 17% to \_\_\_\_\_\_% by 2025. (25)
- 5. The \_\_\_\_\_\_ initiative was launched in 2014 to position India as a global manufacturing hub. (Make in India)
- 6. The \_\_\_\_\_\_ Scheme provides financial incentives for drone manufacturing companies. (PLI)
- 7. The \_\_\_\_\_\_\_ scheme is designed to empower women SHGs with drone technology. (Namo Drone Didi)
- 8. India is known as the "\_\_\_\_\_ of the World" for its strong pharmaceutical industry. (Pharmacy)
  - . The corridor is a major industrial corridor aimed at
- Corridor)

#### **B. Multiple Choice Questions**

- 1. What is the primary purpose of the Namo Drone Didi scheme?
  - a) Empower male entrepreneurs
  - b) Support IT startups
  - c) Empower women-led SHGs in agriculture

- 2. Which platform is used to register drones and gain approvals in India?
  - a) Digital India
  - b) Digital Sky
  - c) Drone India
- a. How much subsidy is offered under the Namo Drone Didi scheme for drone purchases?
  a) 50%
  b) 60%
  c) 70%
  d) 80%
  d) 80%
  e. Mot to the transference of the transfere

  - is one major benefit of using drones in agriculture?
  - Increased manual labor
  - b) Faster internet connectivity

#### c) Efficient pesticide application

- d) Improved transportation of goods
- 6. Which technology is expected to enhance drone intelligence by enabling real-time data analysis?
  - a) Blockchain

b) Virtual Reality

#### c) Artificial Intelligence

- d) Cloud Computing
- 7. Which sector is India known as the "Pharmacy of the World" for its strong presence?

- 8. What is one key challenge faced by India's manufacturing sector? a) High labor costs b) Limited market access c) Infrastructure gaps d) Lack of raw materials Which of the following is ar other that the following is ar other the following is ar other the following is arbor that the following is arbor that the following is arbor that the following is arbor the following is arbor that the following is arbor that the following is arbor the following is arbor the following is arbor the fo
  - a) Bangalore Tech
  - b) Delhi-Mumba Industrial Corridor (DMIC)
  - c) Chennai II
  - d) Pune **Intro**vation Zone

#### C. Short A **h**swer Questions

hat are the primary objectives of the Namo Drone Didi scheme?  $2^{2}$ . How does the Drone Rules 2021 simplify the drone approval process?

- 3. Explain how drones improve agricultural efficiency.
- 4. What factors contribute to India's growing manufacturing sector?
- 5. Describe the role of the "Make in India" initiative in boosting the manufacturing industry.
- 6. What is swarm technology, and how can it improve drone operations?
- 7. What are the key challenges faced by India's manufacturing sector?

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- 8. How does the Production-Linked Incentive (PLI) scheme support manufacturing in India?
- 9. Why is India considered a global leader in pharmaceuticals?
- 10. What role does AI integration play in enhancing drone functionality?

#### REGARDING SESSION 2: DESCRIBE THE CHALLENGES **DEVELOPMENT IN INDIA**

Drones have become a central technology globally, transforming `industries such as agriculture, logistics, defence, healthcare, and infrastructure. In India, the adoption and development of drone technology hold immense potential due to the country's vast geography, diverse needs, and ambitions for technological self-reliance. However, there several challenges that hinder the rapid growth and development (this sector. These challenges can be broadly classified into regulatory, technological, infrastructural, economic, social, and policy-related is the

## **1. Regulatory Challenges**

#### a) Complex Guidelines

India has made significant strides in drone regulations with the introduction of the Drone Rules 2022, which aimed to simplify and liberalize drone usage. However, frequent amendments and a lack of clarity in some provisions kaye created uncertainties for developers, manufacturers, and hese complexities discourage investors and innovators from fully operators comparing to drone-related ventures.

### $\mathcal{O}$ b) Approval Delays

Obtaining permissions for drone operations, especially for Beyond Visual Line of Sight (BVLOS) flights, remains cumbersome. The processes for acquiring certifications, licenses, and security clearances from multiple authorities often result in significant delays, hampering the pace of innovation and deployment.

#### c) Privacy and Security Concerns

The potential misuse of drones for surveillance, espionage, or unauthorized data collection raises critical privacy and security issues. This has led to strict regulatory oversight, which, while necessary, adds additional layers of compliance for legitimate users.

#### 2. Technological Constraints

#### a) Dependence on Imports

India's drone industry heavily relies on imports for critical components such as high-quality sensors, GPS modules, communication systems, and lithium batteries. This dependency not only increases costs by also makes the industry vulnerable to supply chain disruptions and geopolitical tensions.

#### b) Limited Indigenous R&D

The lack of robust research and development (RoD) ecosystems for drones is a significant challenge. While some start ups and institutions are working on indigenous solutions, they often face funding constraints and limited access to advanced testing facilities, slowing the pace of technological advancement.

# c) Battery and Payload Similations

Most drones currently incuse face constraints in flight duration and payload capacity due to baryery inefficiencies. Developing lightweight, high-density batteries and optimizing energy efficiency are critical areas where India needs to focus.

## d) Skilled Workforce

A shortage of skilled professionals proficient in drone design, development, and maintenance further hampers the sector's growth. This skills gap affects not only manufacturing but also operations and innovation in drone applications.

#### **3. Infrastructure Gaps:**

#### a) Manufacturing Ecosystem

India lacks the infrastructure for large-scale manufacturing and assembly of drones and their components. Establishing a robust manufacturing ecosystem, including specialized facilities for prototyping, testing, and production, is essential for scaling up the industry.

#### b) Testing and Certification Facilities

The absence of adequate testing zones and certification facilities possions challenges for developers to evaluate their products in real-world scorarios. This often delays the deployment of new technologies and reduces competitiveness.

#### c) Connectivity Issues

Seamless communication is critical for advanced drone operations, especially BVLOS (beyond visual line of sight) missions. However, India's inconsistent internet and cellular network coverage in rural and remote areas limits the scope of drone deployment in such regions.

#### 4. Economic Challenges

#### a) High Costs

Developing, procuring, and maintaining drones is expensive, especially for start-ups and small enterprises. High upfront costs deter smaller players from entering the market, limiting competition and innovation.

#### b) Limited Investment

While the government has introduced initiatives like the Production-Linked Incentive (PEI) scheme for drones, private investment remains limited. Venture capitalists and institutional investors are often hesitant to fund drom startups due to regulatory uncertainties and the long gestation period for returns.

#### c) Global Competition

India faces intense competition from international drone manufacturers, particularly from countries like China, the United States, and Israel, which have advanced technologies and established supply chains. Competing with these players requires significant investment in R&D and cost optimization.



#### 5. Social and Ethical Concerns:

#### a) Public Perception

Drones are often perceived as intrusive or unsafe, primarily due to concerns about accidents, noise pollution, or unauthorized surveillance. This perception creates resistance to their adoption, especially in urban areas.

#### b) Misuse Potential

The potential misuse of drones for illegal activities, such as gling, spying, or terrorism, poses serious risks. Ensuring robust methanisms to prevent unauthorized usage while fostering innovation is a delicate balance ve that India must achieve. AOL TO

#### **6.** Policy Implementation and Enforcement

#### a) No-Fly Zones

Enforcing no-fly zones around sensitive areas like airports, military installations, and government facilities is challenging. Without advanced geofencing and monitoring system remains compliance remains difficult.

 $\bigcirc$ 

#### b) Standardization Issues

The absence of standardized protocols for drone manufacturing, operation, and interoperability ween different systems limits scalability and integration. Developing uniform standards is crucial for fostering collaboration and widespread adoption.

#### c) Bureau ratic Challenges

Inconsistent enforcement of policies across states and regions creates dispancies in how drone-related businesses operate. Streamlining policy incolementation at both the central and state levels is essential for cohesive development.

#### d) Government Initiatives and the Way Forward

#### e) Regulatory Reforms

The Drone Rules, 2022, represent a step in the right direction by reducing the number of permissions required and introducing digital platforms for

approvals. Further streamlining these processes will encourage participation from innovators and investors.

#### f) Indigenous Development

Promoting indigenous manufacturing through initiatives like Aatmanirbhar Bharat can reduce dependency on imports. Government support for R&D, collaboration with academic institutions, and public-private partnerships can drive technological advancements.

#### g) Training and Skill Development

Launching specialized training programs and academic courses on drone technology can address the skills gap. Establishing certification standards for drone pilots and engineers will also ensure quality and safety.

#### h) Infrastructure Development

Creating dedicated drone corridors, testing zones, and manufacturing hubs can accelerate the industry's growth. Investment in geospatial mapping, 5G connectivity, and advanced air traffic management systems are also critical.

#### i) Public Awareness Campaigns

Educating the public about the benefits and safe use of drones can help address social and ethical concerns. Clear communication about privacy safeguards and safety measures can build trust and acceptance.

#### j) Conclusion

While India has made considerable progress in embracing drone technology, significant chaltenges remain. Addressing regulatory ambiguities, fostering indigenous innovation, developing infrastructure, and ensuring public trust are essential for unlocking the full potential of drones in India. By taking a collaborative and forward-looking approach, India can position itself as a gobal leader in drone technology and harness its benefits for economic growth and societal advancement.

# SESSION 2: DESCRIBE THE CHALLENGES REGARDING DRONE DEVELOPMENT IN INDIA

#### CHECK YOUR PROGRESS

### A. Fill in the Blanks

- The introduction of the \_\_\_\_\_ in 2021 aimed to simplify and liberalise drone usage in India. (Drone Rules)
- India's drone industry heavily relies on imports for critical components such as high-quality sensors, \_\_\_\_\_, and lithium batteries. (GPS modules)
- 3. The absence of adequate \_\_\_\_\_\_ and certification facilities possible challenges for developers to evaluate their products in real-world scenarios. (Testing zones)
- 4. India faces intense competition from international drone manufacturers, particularly from countries like States, and Israel. (China)
- 5. The \_\_\_\_\_\_ scheme introduced by the government aims to promote domestic drone manufacturing. (**Production-Linked Incentive (PLI)**)
- 6. The lack of a skilled \_\_\_\_\_\_ is a pool or barrier to India's drone industry growth.
  Answer: Workforce \_\_\_\_\_\_
- 7. Developing lightweight, high-density \_\_\_\_\_ can improve drone flight duration and payload capacity. (Batteries)
- 8. Aatmanirbhar Brarat is a key government initiative promoting indigenous manufacturing to reduce reliance on. (imports)
- 9. The lack in rural and remote areas limits the effective use of dropes for agricultural and logistics purposes. (Internet connectivity)

10. Establishing dedicated \_\_\_\_\_ corridors can enhance drone operations and ensure safe flight paths. (Drone)

### **B. Multiple Choice Questions**

- 1. Which year did India introduce the Drone Rules to simplify drone usage? a) 2019
  - b) 2020
  - c) 2021

d) 2022

2. What is one of the key technological constraints faced by the Indian drone industry? a) Over-reliance on domestic manufacturing

### b) Dependence on imports for critical components

- c) Excessive government subsidies

- 3. Which major issue results from battery inefficiencies in dronkis the dramatic in a) Increased noise pollution
  b) Reduced payload capacity and flight duration
  c) Higher labor costs
  d) Limited visual quality in surveillance
  4. Which of the following is NOT. industry? a) Complex guidelines
  - b) Approval delays

### c) Manufacturing ecosyst condevelopment

- d) Privacy and security concerns
- 5. What is a major momic challenge faced by Indian drone startups?
  - a) Overproduction of drones
  - s and limited investment b) High **go**
  - tenvironmental standards
  - cessive foreign competition

What is a significant social concern associated with drone usage in India?

a) Excessive maintenance costs

### b) Misuse for illegal activities

- c) Limited range in rural areas
- d) Poor visual quality

7. What is a critical infrastructural gap that hinders India's drone industry? a) Lack of educational courses

### b) Poor internet connectivity in rural areas

- c) Strict safety regulations
- d) Lack of customer demand

gital India
9. Which sector in India can greatly benefit that improved drone connectivity in rural areas?
a) Entertainment
b) Banking
c) Agriculture
d) Fashion dy Material

- 10. What type of flig peration faces delays due to complex approval processes in L
  - a) Visual the of Sight (VLOS)
  - b) Bexond Visual Line of Sight (BVLOS)
  - tomated Drone Delivery (ADD)
  - Manual Drone Navigation (MDN)

### **C. Short Answer Questions**

- 1. What are some of the key regulatory challenges faced by India's drone industry?
- 2. How does India's dependence on imported drone components impact the industry?

- 3. What steps can be taken to improve India's indigenous drone R&D ecosystem?
- 4. What role does the Production-Linked Incentive (PLI) scheme play in drone manufacturing?
- 5. How can the public perception of drones be improved in India?
- 6. What is the significance of BVLOS operations in drone technology?
- 7. Why is establishing dedicated drone corridors important for India's drone industry?
- 8. How can India's skilled workforce gap in the drone industry addressed?
- 9. What role does 5G connectivity play in enhancing drope operations?
- 10. What steps can be taken to ensure drones are used ethically and responsibly in India?

### **Answer Key**

MODULE 1. ASSEMBLING/DISASSEMBLING PROCESSING OF DRONE

### Session 1: Assembling/Disastembling of Drones

### A. Fill in the Blanks

- 1. Always turn o
- 2. Assembly
- 3. Flight controller
- 4. Malfunction or fail to operate
- 5. Electronic

### B. Malliple Choice Questions

- 1. c) Assembling the frame
- 2. b) At the center of the frame
- 3. b) To prevent vibrations and instability
- 4. b) To distribute power from the battery to different components
- 5. b) Check all connections and test each component
- 6. a) Removing the battery
- 7. a) To prevent injury or damage
- 8. a) To avoid losing parts and protect them from damage
- 9. c) Performing a test

### **Session 2: Power Architecture of Drone**

### A. Fill in the Blanks

- 1. Lithium Polymer
- 2. Power Distribution Board
- 3. Electronic Speed Controllers
- 4. Flight Controller

### **B.** Multiple Choice Questions

- ..., user (LiPo) ..., C) Controls the speed and direction of brushless motors 3. b) They have a higher energy density and lightweight design it is 4. b) To distribute power from the battery to different common 5. a) Battery capacity and motor efficiency: sion 2: 5.

### dy Material Not Session 3: Software Architecture and Communication Module

### A. Fill in the Blanks

- 1. Sensor
- 2. Control
- 3. Planning
- 4. Communication
- 5. Application
- 6. Flight Control System
- 7. Navigation
- 8. Communication

### B. Multiple Choice Questions

- 1. b) Sensor Lag
- 2. c) Flight Control System
- 3. c) Microsorvices Architecture4. c) With
- 5. b) Rayload Control System
- 6. Communication Layer
- (a) Navigation System
- 8. c) Cellular Networks
  - 9. a) PID Control
  - 10. b) Latency

### **MODULE 2: REPAIR AND MAINTENANCE**

### **Session 1: Drone Maintenance and Operations**

### A. Fill in the Blanks

- 1. Routine
- 2. Battery
- 3. Software
- 4. Loose
- 5.90
- 6.15
- 7.30
- 8. 40-60
- 9. Vibrations

# A Fill in the Blanks A Fill in the Blanks A Fill in the Blanks A Recalibrate 4. VTX Cache Cache A Replace A Magnetic Cache A Replace A Magnetic Cache C

- 10. Powe

### B. Multiple Choice Questions

- 1. b) Check battery connectors for dirt or corrosion
- 2. c) Firmware updates
- 3. b) Compass
- 4. c) Switch to a different FPV channel
- 5. a) Decrease video transmission power
- 6. b) Calibrate the gimbal through the flight app
- 7. c) Restart the drone and wait for 10-12 satellites
- 8. c) Battery degradation after multiple cycles
- 9. b) Ensure compatibility with the drone's flight system

10. c) Use a stable internet connection and try updating via USB

### Session 3: Drone Life Cycle Management

### A. Fill in the Blanks

- 1. Acquisition
- 2. Safety
- 3. Planning
- 4. FAA
- 5. Software

### **B. Multiple Choice Questions**

- 1. c) Storage and Packaging
- 2. b) Ensuring safe, efficient, and t-effective drone operation
- 3. b) Budget constraints and operational needs
- 4. a) FAA
- 5. b) Fleet Management System
- 6. b) Checking battery health and updating firmware
- 7. a) Battery
- 8. b) To safely retircine drone and dispose of its components
- 9. c) Data-wiping protocols
- 10. c) Updating comera resolution

### Session 4: Formats for Repair and Maintenance

- A. Fill in the Blanks
  - Phecklists, Reports
- 2. Incident
  - 3. Flight test
  - 4. Repair
  - 5. Regular
  - 6. Inventory
  - 7. Budgets
  - 8. Legal and Safety
  - 9. Insurance
  - 10. Cycle

- Batteries Published 9. Environmentape 10. Dispto Lent Disposa

### **B.** Multiple Choice Questions

- 1. b) Reports
- 2. b) Incident reports
- 3. c) Repair reports
- 4. c) Flight test log
- 5. a) Maintenance schedule
- 6. b) Parts inventory log
- 7. b) Repair cost estimate
- 8. b) Incident report
- 9. b) Battery replacement before degradation
- 10. c) Maintenance records

## MODULE 3: OPPORTUNITIES, RULES AND REGULATIONS egut be not to be not to be not to be

### Session 1: Career in the Drone Industry

### A. Fill in the Blanks

- 1. Remote Pilot Certificate
- 2. Mechanical
- 3. 5G
- 4. Drone Data Analyst
- 5. Drone Delivery
- 6. Drone Pilot
- 7. Drone Engineer
- 8. Aeronautical
- 9. Crop health monitoring
- 10. Drone Instructor

### B. Multiple Choiçe Questions (MCQs)

- 1. b) DGCA Remote Pilot License
- 2. c) Software Engineering
- 3. c) Arone Technician
- 4. Agriculture
- A) Strong hand-eye coordination
- b) Electrical Engineering
- 7. b) Drone Entrepreneur
- 8. c) Advancements in AI and Autonomy
- 9. c) Aeronautical Engineer
- 10. c) Communication

### Session 2: Drone Regulations in India

### A. Fill in the Blanks

blished

- 1. 250 grams
- 2. 2 kilograms
- 3. Digital Sky
- 4. 15 days
- 5. Equipment Type Approval (ETA)
- 6. Airplanes, rotorcraft, hybrid unmanned aircraft
- 7. Flight control module, remote pilot station
- 8.10
- 9. third-party
- 10. Unique Identification Number (UIN)

### **B. Multiple Choice Questions (MCQs)**

- 1. c) 250 grams
- 2. c) 100 ft
- 3. c) Digital Sky
- 4. c) 200 ft
- 5. d) WPC Wing
- 6. a) Remote Pilot Certificate (RPC)
- 7. c) 10 years
- 8. c) Nano drone
- 9. c) Medium drones
- 10. b) 18 years
- rial Not to be Published DEVELOPMEN AND MODULE **INNOVATION** 4: IN DRONE TECHNOLOGY

Session 1: Drone Inpovation and Manufacturing Capabilities in India

- A. Fill in the Bla
  - 2021 1. Drone Ro
  - 2. Digit
  - З.

  - ce in India
  - PLI
  - 7. Namo Drone Didi
    - 8. Pharmacy
  - 9. Delhi-Mumbai Industrial Corridor

### **B.** Multiple Choice Questions

- 1. c) Empower women-led SHGs in agriculture
- 2. b) Digital Sky
- 3. d) 80%

- 4. b) Make in India
- 5. c) Efficient pesticide application
- 6. c) Artificial Intelligence
- 7. c) Pharmaceuticals
- 8. c) Infrastructure gaps
- 9. b) Delhi-Mumbai Industrial Corridor

# Session 2: Challenges Regarding Drone Development in India

### A. Fill in the Blanks

### **B.** Multiple Choice Questions

**AC:** Alternating current

**UAV:** Unmanned Aerial Vehicle

**UAS:** Unmanned Aircraft System

**RPAS:** Remotely Piloted Aircraft System

**RPA:** Remotely Piloted Aircraft

**RPIC:** Remote Pilot in Command **VLOS:** Visual Line of Sight **BVLOS:** Beyond Visual Line of Sight **GPS:** Global Positioning System **RTK:** Real-Time Kinematic Material Not to be Published **FPV:** First-Person View **LiDAR:** Light Detection and Ranging **ESC:** Electronic Speed Controller FC: Flight Controller **PPK:** Post-Processed Kinematic **GIS:** Geographic Information System **NDVI:** Normalized Difference Vegetation Index **SLAM:** Simultaneous Localization and Mapping **LOS:** Line of Sight **IMU:** Inertial Measurement Unit **GSD:** Ground Sample Distance **GCP:** Ground Control Point **AoA:** Angle of Attack LiPo: Lithium-Polymer Battery ROI: Return on Investment CAA: Civil Aviation Authority **NOTAM:** Notice to Airmen LandD: Launch and Delivery **RTH:** Return to Home  $\mathbf{X} \mathbf{Y}$ **SOP:** Standard Operating Procedure **COA:** Certificate of Authorization **BO**: **Direct Current** Kw/Kwh: Kilowatt/kilowatt-hour W/Wh: Watt/watt-hour Wp: Peak Watt, also known as Watt-peak DGCA: DIRECTORATE GENERAL OF CIVIL AVIATION

**MOCA:** Ministry of Civil Aviation

**GCS:** Ground Control Station

- GDT: Ground Data Terminal
- VTOL: Vertical Take-off and Landing
- BLDC: Brushless Direct Current
- RPC: Remote Pilot Certificate
- **RPTO: Remote Pilot Training Organization**

PSSCWE Dratt Study Material Not to be Published

### GLOSSARY

### Ampere (Amp) — a unit of electrical current or rate of flow of electrons.

**Battery** — Two or more electrochemical cells enclosed in a container and electrically interconnected in an appropriate series/parallel arrangement to provide the required operating voltage and current levels. under common usage, the term battery also applies to a single cell if it constitutes the entire electrochemical storage system.

**Battery Capacity** — The maximum total electrical charge, expressed in ampere-hours, which a battery can deliver to a load under a precific set of conditions.

Battery Cell - The Simplest Operating Unit in A Storage Battery.

**Battery Life** — The Period During Which a Celfor Battery Is Capable of Operating Above a Specified Capacity or Efficiency Performance Level. Life May Be Measured in Cycles and/or Years, depending on the Type of Service for Which the Cell or Battery Is Intended.

**Drone:** An unmanned aerial vehicle (UAV) or unmanned aircraft that can be remotely controlled or operate autonomously.

**Drone Service Technician:** A professional who specializes in operating, maintaining, and troubleshooting drones for various applications.

**Remote Pilot:** Operson who controls a drone's flight using a remote controller or a ground-based control station.

**Payload** The equipment or sensors carried by a drone, such as cameras, LiDAT, thermal imagers, or other specialized tools.

**MDAR:** Light Detection and Ranging is a technology that uses laser pulses to measure distances, commonly used for creating high-resolution 3D maps.

**FPV (First-Person View):** A method that allows the drone operator to see the drone's perspective in real-time through a live video feed transmitted from the drone's camera.

**RTK (Real-Time Kinematic):** A satellite navigation technique used to enhance the precision of the drone's positioning data.

**Waypoints:** Pre-defined GPS coordinates that are programmed into the drone's flight path, allowing it to fly along a predetermined route.

**Gimbal:** A stabilized camera mount that allows the camera to maintain a level horizon, even if the drone tilts or moves.

**ESC (Electronic Speed Controller):** A device that regulates the speed of the drone's motors based on signals from the flight controller.

Flight Controller: The main onboard computer system the manages the drone's flight, navigation, and stabilization.

**Remote Sensing:** The process of gathering data from a distance, often using sensors on a drone to collect information about the environment.

**Resistance (R)** — the property of a conduct  $\mathfrak{F}$  which opposes the flow of an electric current  $\cdot \mathfrak{F}$ 

**Georeferencing:** The process of as ociating data collected by the drone with specific geographic coordinates to create accurate maps or models.

**Point Cloud:** A collection of 3D points generated by LiDAR or photogrammetry, used to create detailed 3D models of terrain or structures.

**Photogrammetry:** A technique that uses photographs taken from different angles to create 3D models or maps of objects or landscapes.

**GIS (Geographic Information System):** A system that stores, analyzes, and Osplays geographic data, often used to process drone-acquired data.

**BVLOS (Beyond Visual Line of Sight):** Refers to drone operations conducted outside the pilot's direct visual range, often requiring special permissions and technology.

**NOTAM (Notice to Airmen):** Information issued by aviation authorities to alert drone operators to potential hazards or operational restrictions in a specific area.

**LiPo Battery (Lithium-Polymer Battery):** A common type of battery used in drones due to its high energy density and lightweight characteristics.

**UTM (Unmanned Traffic Management):** Systems and technologies designed to manage and integrate drone traffic into the airspace safely.

**Conductor** — The material through which electricity is transmitted, such as an electrical wire, or transmission or distribution line.

**Deep Discharge** — Discharging a battery to 20% or less of its full charge capacity.

Electric Current — The flow of electrical energy (electricity) a conductor, measured in amperes.

Load — The Demand on an Energy-Producing System

**Ohm** — A Measure of the Electrical Resistance **O** a Material Equal to The Resistance of a Circuit in Which the Potential Difference Of 1 Volt Produces A Current Of 1 Ampere.

**DIGITAL SKY**- Digital Sky is an opkie platform that manages unmanned aircraft systems (UAS) in India was developed by the Directorate General of Civil Aviation (DGCA)

ANTI-DRONE SYSTEM

AIR SPACE MAP- X URBAN AERIAD MOBILITY-

REFERANCE LINK

- 1. <u>https://digitalsky.dgca.gov.in/</u>
- 2. <u>https://ardupilot.org/planner/</u>
- 3. https://www.civilaviation.gov.in